Exact learning and inference for planar graphs

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Ising model



- Particles modify their behaviour to conform with neighbours' behaviour
- What is the mean energy?
- Used in chemistry, physics, biology...
- More than 12,000 papers published!

Ising problem

- Graph G = (V, E)
- Binary variables: $x_i \in \{-1, +1\}$
- No potential for disagreement edges: $\phi_{ij} = 0$ if $x_i \neq x_j$
- Model distribution

$$P(x) = \frac{1}{Z(\phi)} e^{\sum_{ij \in E} [x_i = x_j]\phi_{ij}}$$
, where

$$Z(\phi) = \sum_{x} e^{\sum_{ij \in E} [x_i = x_j]\phi_{ij}}$$
 is the partition function

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- How many perfect matchings does a graph have?
- **Perfect Matching**: A set of non-overlaping edges (dimers) that cover all vertices



Counting Matchings

• Construct a **Pfaffian orientation**: each face (except possibly outer) has an odd number of edges oriented clockwise



• Construct a skew-symmetric matrix *K* such that:

$$K_{ij} = \begin{cases} 1 & \text{if } i \to j \\ -1 & \text{if } i \leftarrow j \\ 0 & \text{otherwise} \end{cases}$$

• Kasteleyn Theorem:

- Every planar graph has a Pfaffian orientation
- Number of perfect matchings is $Pf(K) = \sqrt{\det K}$

- Let G_{\triangle} be G plane triangulated: each face becomes a triangle
- Let G^* be the dual of graph G_{\triangle} : each face in G_{\triangle} is a vertex in G^*
- Let G_e^* be the expanded version of G^* : each vertex is replaced with 3 vertices in triangle
- Connection: There is a 1:1 correspondence between agreement edge sets in G and perfect matchings in G_e^*

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- State-of-the-art exact method for computing partition function, marginals and MAP assignment
- Graph is a tree: complexity polynomial in graph size
- Graph is **not a tree**:
 - Convert the graph into a tree of cliques
 - Complexity exponential in maximal clique size

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- Globerson & Jaakkola 2006 use previous results (Ising model) to compute the partition function exactly
- Restrictions:
 - Graph is planar (no crossing edges)
 - Binary-valued labels
 - Only edge potentials, no external field (node potentials)
- Complexity polynomial in graph size!

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- Faster and simpler version of Globerson and Jaakkola algorithm
- No need to compute the dual G^* and expanded version G_e^*
- Showed how to compute gradients and hence perform learning
- Applied to territory prediction in Go





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- Obtain a planar embedding
- Using Boyer-Myrvold algorithm the complexity is O(V + E)



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- Plane triangulate the graph
- Using simple ear-clipping the complexity is $O(V^2)$



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- Orient the edges such that each vertex has odd in-degree
- Equivalent to having a Pfaffian orientation in the dual graph
- Complexity is O(E)



- Construct a skew-symmetric 2*E* × 2*E* matrix K (for dual edges):
 - $K_{ij} = \pm e^{\phi}$ if *ij* crosses **original** edge
 - $K_{ij} = \pm 1$ if *ij* crosses added edge
- Complexity is O(2E)





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- Compute partition function: $Z(\phi) = 2 \sqrt{\det K}$
- Compute gradients: $\frac{\partial \ln Z(\phi)}{\partial \phi_k} = -[K^{-1} \odot K]_{2k-1,2k}$
- Computing inverse and determinant takes complexity $O(E^3)$

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Go application



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Results

- It works correctly computes partition function and gradients
- Overall complexity is $O(E^3)$
- Performance

Training Size	Error		
	Block	Vertex	Game
100	3.17 ± 0.18	2.32 ± 0.06	10.93 ± 1.04
1000	2.79 ± 0.17	1.94 ± 0.05	9.71 ± 0.98
2000	3.06 ± 0.18	2.17 ± 0.05	9.71 ± 0.98
5000	2.76 ± 0.17	1.87 ± 0.05	9.60 ± 0.98
10000	3.20 ± 0.18	2.27 ± 0.06	10.04 ± 1.00

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Questions?

"Some cause happiness wherever they GO, others whenever they GO" - Oscar Wilde

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