

So $V(\varphi) = \int_U (1 + \sum_{i=1}^n a_i^2) / (1 + \sum_{i=1}^n a_i^2)^{1/2} = \int_U (1 + \sum_{i=1}^n (\partial g / \partial u_i)^2)^{1/2}$.

17.8 (a) Prove $J\varphi_n$ is not singular. We prove by induction. When $n=2$, $J_2 = \begin{pmatrix} \cos \theta_1 \sin \theta_2 & -\sin \theta_1 \sin \theta_2 & 0 \\ \sin \theta_1 \cos \theta_2 & \cos \theta_1 \cos \theta_2 & -\sin \theta_1 \end{pmatrix}$
 $\text{rank } J_2 = \text{rank } J_2 \cdot J_2^T = \text{rank} \begin{pmatrix} \sin^2 \theta_2 & 0 \\ 0 & 1 \end{pmatrix} = 2$, So J_2 is fully ranked. Suppose $\text{rank } J_{n-1} = n-1$.

Denote the (i,j) th component of J_n as $J_n^{i,j}$, $i=1 \dots n+1, j=1 \dots n$. then
 $J_n = \begin{pmatrix} J_{n-1} \sin \theta_n & \dots & -J_{n-1}^T \sin \theta_n & \varphi_n \\ 0 & \dots & 0 & -\sin \theta_n \end{pmatrix} = \begin{pmatrix} \sin \theta_n \cdot J_{n-1} & \varphi_n \cos \theta_n \\ 0 & -\sin \theta_n \end{pmatrix}$, so $\text{rank } J_n = n-1+1 = n$. i.e., φ_n is parametrized n -surface.

(b) φ_n maps U one to one onto a subset of unit n -sphere S^n : $(a_1, \dots, a_{n+1}) \mid \sum_{i=1}^{n+1} a_i^2 = 1$.
 Let φ_n^i be the i th component of φ_n . then $\sum_{i=1}^{n+1} \varphi_n^{i2} = 1$. So φ_n maps U to a subset of S^n .

We only need to prove one to one. If $\varphi_n(\theta_1, \dots, \theta_n) = \varphi_n(\hat{\theta}_1, \dots, \hat{\theta}_n)$, then $\cos \theta_n = \cos \hat{\theta}_n$, As $\theta_n, \hat{\theta}_n \in (0, \pi)$, so $\theta_n = \hat{\theta}_n$, as $\sin \theta_n \neq 0$ so

$\varphi_{n-1}(\theta_1, \dots, \theta_{n-1}) = \varphi_{n-1}(\hat{\theta}_1, \dots, \hat{\theta}_{n-1})$. For the same reason, we have $\theta_{n-1} = \hat{\theta}_{n-1}, \dots, \theta_2 = \hat{\theta}_2$.

Finally $(\sin \theta_1, \cos \theta_1) = (\sin \hat{\theta}_1, \cos \hat{\theta}_1)$. As $\theta_1, \hat{\theta}_1 \in (0, 2\pi)$, $\theta_1 = \hat{\theta}_1$. Thus φ_n is one to one.

(c) If $x \in S^n - \text{Image } \varphi_n$, then $\prod_{i=1}^n \sin \theta_i = 0$. This is because if $\prod_{i=1}^n \sin \theta_i \neq 0$, $\varphi_n(\theta_1, \dots, \theta_n)$ It is obvious that $\hat{\varphi}_n: U' \rightarrow R^{n+1}$ with $U' = \{(\theta_1, \dots, \theta_n) \in R^n \mid 0 < \theta_i < 2\pi, 0 < \theta_i < \pi \mid i \in \{2, n\}\}$ maps onto S^n . So if $x = \hat{\varphi}_n(\theta_1, \dots, \theta_n) \in S^n - \text{Image } \varphi$, then $(\theta_1, \dots, \theta_n) \in U' \setminus U$.
 So $\prod_{i=1}^n \sin \theta_i = 0$ so $x_1 = 0$. Thus $S^n - \text{Image } \varphi$ is contained in the $(n-1)$ -sphere $\{(x_1, \dots, x_{n+1}) \in S^n \mid x_1 = 0\}$. So $V(\varphi_n) = V(S^n)$

(d) $|J_n| = \begin{vmatrix} \sin \theta_n \cdot J_{n-1} & \varphi_n \cos \theta_n & \varphi_n \sin \theta_n \\ 0 & -\sin \theta_n & \cos \theta_n \end{vmatrix} = \begin{vmatrix} \sin \theta_n \cdot J_{n-1} & \varphi_n \cos \theta_n & \varphi_n \sin \theta_n \\ 0 & -\sin \theta_n & 0 \end{vmatrix} = (\sin \theta_n)^n |J_{n-1} \varphi_{n-1}| = (\sin \theta_n)^n |J_{n-1}|$

So $V(\varphi_n) = \int_0^\pi (\sin \theta_n)^n d\theta_n V(\varphi_{n-1})$ for $n \geq 3$, $V(\varphi_2) = 4\pi$

(e) Note the fact: $I_n = \int_0^\pi (\sin \theta)^n d\theta = \frac{n-1}{n} \int_0^\pi (\sin \theta)^{n-2} d\theta = \frac{n-1}{n} I_{n-2}$ for $n \geq 2$.

$I_1 = 2, I_2 = \pi/2, I_0 = \pi$. $I_n = \frac{(n-1)!!}{n!!} \pi$ if n is even and $I_n = \frac{(n-1)!!}{n!!} 2$ if n is odd

So $V(\varphi_n) = I_n \cdots I_3 V(\varphi_2) = 4 \prod_{k=1}^n I_k$, ($n \geq 2$).

17.9 Denote $v_i = \frac{\partial \varphi}{\partial u_i}$ ($i=1, 2$). $N = v_1 \times v_2 / \|v_1 \times v_2\|$.

$A(\varphi) = \int_U \frac{|v_1 \times v_2|}{\|v_1 \times v_2\|} / \|v_1 \times v_2\| = \int_U (v_1 \times v_2) \cdot (v_1 \times v_2) / \|v_1 \times v_2\| = \int_U \|v_1 \times v_2\|$

17.10 (a) By Ex 14.9, W is normal vector field along φ . $\frac{E_i(\varphi)}{E_i(\varphi)} = \sum_{i=1}^n W_i^2 \geq 0$. So $W/\|W\|$ is the orientation vector field along φ .

(b) $V(\varphi) = \int_U \frac{E_i(\varphi)}{E_i(\varphi)} = \int_U W \cdot W / \|W\| = \int_U \|W\|$

17.11 Let $\varphi = (e_1, \dots, e_n)$ with $e_i = (0, \dots, 0, 1, 0, \dots, 0) \in R^n$, $A = (E_1^\varphi, \dots, E_n^\varphi, N^\varphi)$, $B = (E_1^\varphi, \dots, E_n^\varphi, N^\varphi)$