

# Challenges in Large-scale Electromagnetic Compatibility Analysis

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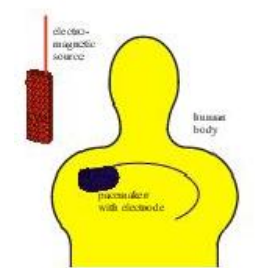
# 1 Talk Outline

- introduction to EMC analysis
- the ACCUFIELD application:
  - introduction
  - fast frequency stepping
  - direct solution methods
  - iterative solution methods via fast frequency stepping
  - performance and convergence issues
- related work in EMC
- challenges for large-scale analysis
- where to go from here?

## 2 Introduction to Electromagnetic Compatibility Analysis

- Electromagnetic Compatibility (EMC) issues becoming increasingly important
  - ↑ GHz (microwave) clock speeds, increasingly complex electronic systems
  - an (oscillating) incident electromagnetic field may induce locally very strong currents and resultant fields on an electronic device
  - concern over health & system malfunction issues due to electromagnetic interference (EMI)
    - ⇒ strict EMC regulations imposed by most countries

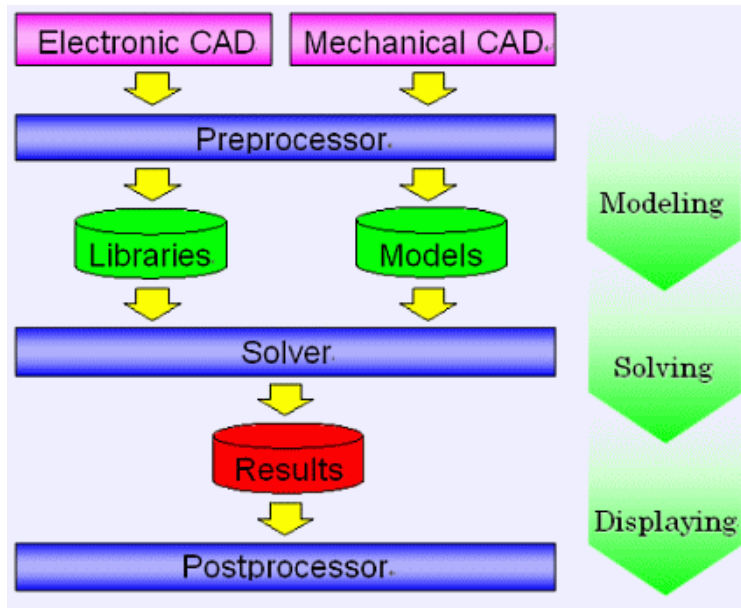
- ⇒ need accurate prediction of EMI at the system design stage



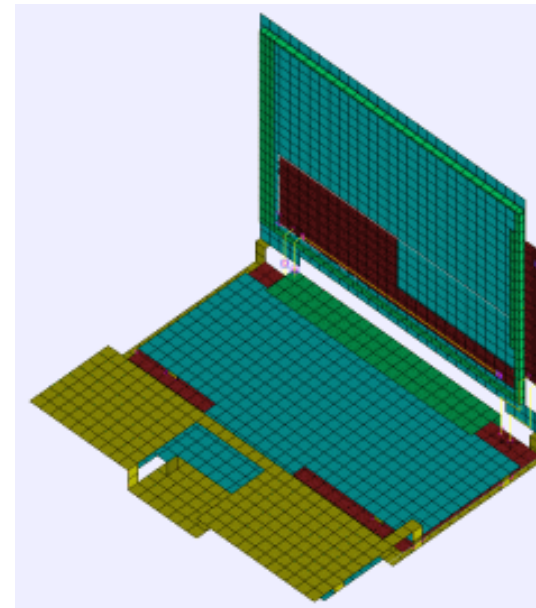
- the electromagnetic scattering problem is closely related

### 3 Introduction to ACCUFIELD

- ACCUFIELD is such an application ([www.accufield.com](http://www.accufield.com), Fujitsu)



ACCUFIELD architecture



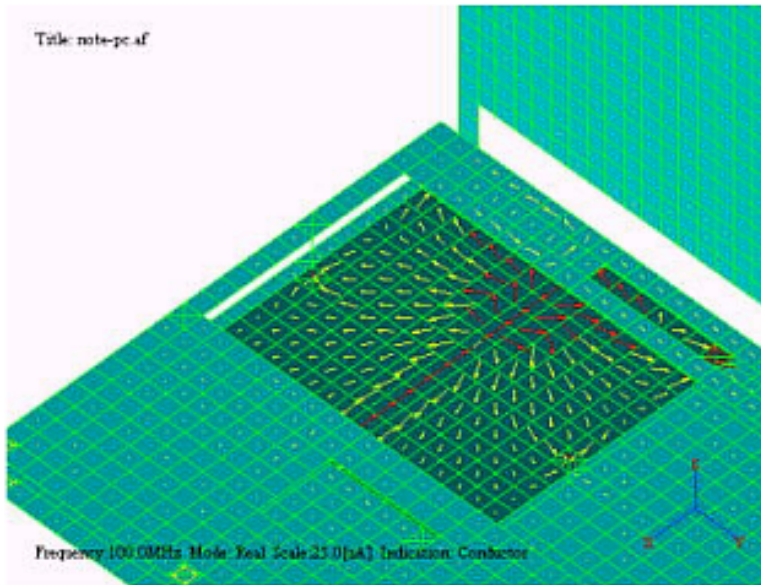
Note PC model

- used mainly for relatively simple electronic devices, eg. printed circuit boards
- uses the moment & transmission line approximation methods to calculate the EM field in the frequency domain (details on [www](http://www.accufield.com) page)
- models: break conductive & dielectric surfaces / wires into discrete elements

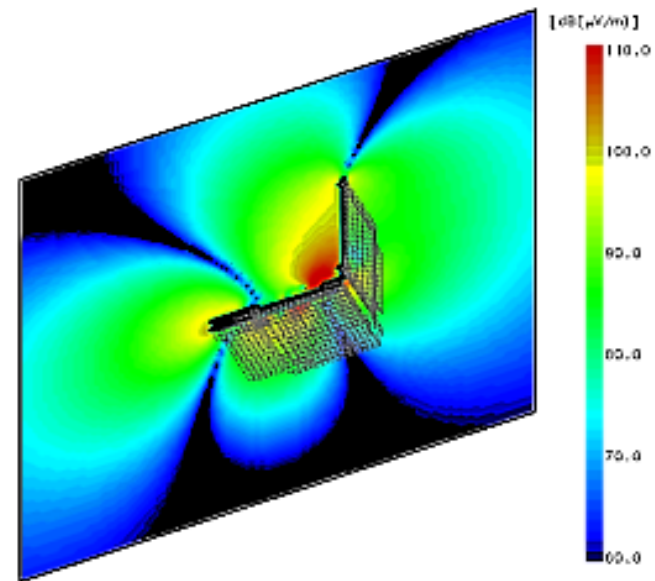
- given an incident (oscillating) electric field  $V$  (known), find the induced current  $I$  from  $ZI = V$ , where:
  - $Z$  is a dense complex (indefinite)  $N \times N$  matrix
    - assembled using the relatively compact model description
    - normally symmetric, unless constraints are imposed
  - for Note PC model,  $N = 7041$ , but  $N \approx 30000$  possible for large-scale systems
  - symmetric: direct solution via  $Z \rightarrow PLDL^T P^T$  requires  $\frac{N^3}{3}$  FLOPs,  $\approx \frac{N^2}{2}$  storage
    - store  $Z$  in lower triangular half; overwrite with  $L$  and  $D$
    - $\Rightarrow$  a large || parallel machine is required eg. AP3000, 24 nodes @ 300 MHz, 1.5GB
  - non-symmetric: direct solution via  $Z \rightarrow PLU$ ,  $2 \times$  as many FLOPs & storage
- EMC analysis is usually required at different frequencies  $\omega$ 
  - here  $V = V(\omega)$ ,  $Z = Z(\omega)$ ; the direct solution at  $\omega_c$  can be used to precondition an  $O(N^2)$  iterative solution for  $\omega \approx \omega_c$

- using the solution vector  $I$ , can determine the induced surface fields, current emissions, the effectiveness of filters and shielding, etc
  - FFTs are used to convert results to the time domain

• eg.



current vector diagram



EM field map

## 4 Fast Frequency Stepping in ACCUFIELD

- consider a analysis over set of frequencies  $\Omega = \{\omega_1, \omega_2, \dots, \omega_{n_f}\}$ ,  $\omega_i < \omega_{i+1}$
- for linear system assembly:
  - using the model's information, explicitly assemble  $Z(\omega_j)$  for  $\omega_j \in \Omega_s \subseteq \Omega$
  - for  $\omega_i \notin \Omega_s$ , interpolate  $Z(\omega_i)$  from  $Z(\omega_j), Z(\omega_k)$ , where  $j < i < k$  and  $\omega_j, \omega_k \in \Omega_s$
  - (embarrassingly) easy to parallelize
- for linear system solution:
  - choose a central frequency  $\omega_c$ , eg.  $\omega_c \in \Omega_s$ , and obtain a direct solution here
  - the factorized  $Z(\omega_c)$  is used to precondition the iterative solutions for  $\omega_i$  to left and right of  $\omega_c$
  - do this until the iterative solution time  $>$  half the direct solution time
- these methods represents space-time tradeoff

## 5 Direct Solution of Indefinite Systems

- a direct solution for  $I$  is the most general and potentially accurate method
- symmetric systems:
  - numerically stable algorithms exist that exploit symmetry to require only  $\frac{N^3}{3} + O(N^2)$  FLOPS in the factorization:
    - (row/column) symmetric interchanges are required to eliminate some columns
    - the Bunch-Kaufman LDLT factorization algorithm  $Z \rightarrow PLDL^T P^T$  has been shown to be very competitive!
    - we have developed especially efficient serial and || implementations
  - back-solve computation performs:  $I = V; I \leftarrow P^{-T} L^{-T} D^{-1} L^{-1} P^{-1} I$ 
    - has only  $O(N^2)$  FLOPs, but high  $O(N)$  associated || overheads
    - is also used for preconditioning in the iterative solver
- non-symmetric systems: LU factorization is well-known; back-solve computation  $I \leftarrow U^{-1} L^{-1} P^{-1} I$  has slightly lower overheads



## 6 Iterative Solution for Fast Frequency Stepping

- use a preconditioned conjugate gradient method, adapted for indefinite symmetric systems
  - nb. ACCUFIELD usually generates “nearly” definite systems
- each iteration requires:
  - a symmetric matrix-vector multiply  $r \leftarrow r - \alpha Z(\omega_i)p$
  - a back-solve via the factored preconditioner  $p \leftarrow \beta p + Z^{-1}(\omega_c)r$
  - miscellaneous vector operations (adding a small amount of extra overhead)
- $Z(\omega_i)$  and the factored  $Z(\omega_c)$  are stored in an  $N \times (N + 1)$  rectangular matrix
  - physical memory storage requirements still increases by  $2 \times$  (very large  $N$ )
- for large matrices, (||) execution time is dominated by the matrix-vector multiply
- for smaller matrices, time is dominated by communication startups

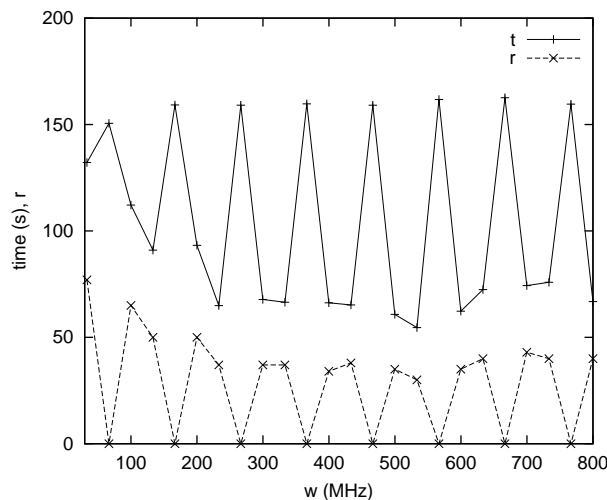
## 7 Performance: Convergence and Computational Speed

- results here are for an 8-node Fujitsu AP3000 with 360 MHz US-2 processors (startup cost  $\approx 20\mu s$ , transfer rate of up to 80 MB/s)

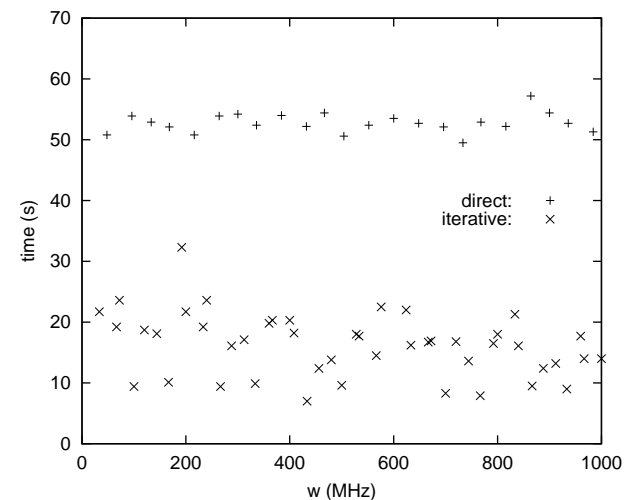
- for analysis of the Note PC model using direct solution:

|            |     |     |    |
|------------|-----|-----|----|
| # cells :  | 1   | 4   | 8  |
| times (s): | 293 | 103 | 59 |

- parallel execution times ( $r$  is the convergence rate):



POS terminal,  $N = 7017$   
 (overall FFS speedup of 1.65;  
 at most 2 iterative solves per  $\omega_c$ )



Note PC model,  $N = 4608$   
 (overall FFS speedup of 2.18;  
 nearby  $\omega$  'pairs' converged rapidly)

## 8 Related Work in EMC

- frequency interpolation proposed for non-symmetric systems by Hoyler and Unbehauen (1996)
    - +ve comparisons with other (eg. block-Jacobi and GMRES) preconditioners
    - their FFS proceeds only in a single direction
  - FFS is a special case of Model-Based Parameter Estimation (Miller, 1998)
    - shows how interpolation can reduce computational work on both the linear system assembly and solution
  - iterative methods for EMC reported by Jakobus (2000)
    - used a conjugate gradient method with a block-Jacobi preconditioner
    - improvements reported for non-symmetric systems
    - no frequency interpolation was used
  - fast multipole methods have been used in electromagnetic scattering
    - Boeing (1999), Jakobus (2000)
- can also use wavelets and adaptive integral methods

## 9 Challenges for Large-scale EMC analysis

- EMC analysis using the moment method can be highly accurate
- combination of direct and iterative methods used in ACCUFIELD:
  - scalable & 'efficient' implementations have been devised
  - symmetry: halves the FLOPs (direct solution only) and storage
  - parallel processing enables feasible solution of moderate-scale systems
- iterative methods for analysis over multiple frequencies
  - still needs  $\parallel$  processing;  $\parallel$  overheads  $\Rightarrow$  only moderate performance gains
  - seems to require an expensive preconditioner; has extra memory costs
- in EMC, larger-scale systems can arise from more complex models and/or finer discretizations (more accurate)
  - need fundamentally less expensive methods than the direct:
  - **problem:** difficulty in achieving good convergence rates
    - effects of dielectric materials
    - most analysed systems are neither large nor elongated
    - large off-diagonal 'mass' of the resulting linear system

## 10 Large-scale EMC analysis: where to go from here?

- (||) out-of-core solvers (direct solution only?)
- better iterative schemes:
  - eg. (symmetric) quasi-minimum residual ?
- better / less expensive preconditioners:
  - eg. block-Jacobi, sparse approx. inverse?
- incorporation of  $O(N \log N)$  techniques (wavelets, FMM, AMI)
  - usable for preconditioners if not sufficiently accurate?
- efficient and portable implementations are needed
- seeking collaborators (from 'advisory' to 'active'...)
- possibility of collaboration with the ACCUFIELD group:
  - strategy: development on the math. rather than the modelling level, use sample linear systems