Automated Reasoning for Situational Awareness

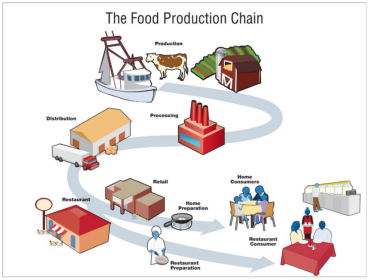
Peter Baumgartner, Alexander Krumpholz

Supply Chain Integrity Digital Mission

www.data61.csiro.au

Situational Awareness - Systems of Interest

- **Factory Floor**
  - Are the operations carried out according to the schedule?
- **Food Supply Chain**



  - Are goods delivered within 3 hours and stored below 25℃?
  - Why is the truck late?
  - Where did the strawberries/honey come from?
- **Data Cleansing**
  - Does the database have complete, correct, accurate and relevant data?

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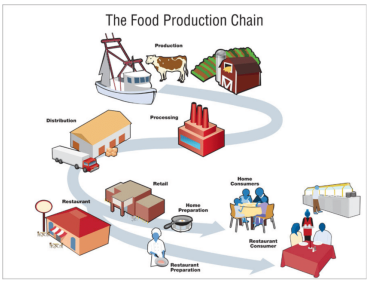

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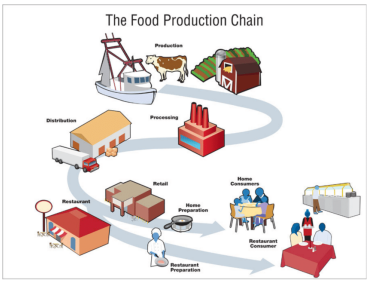

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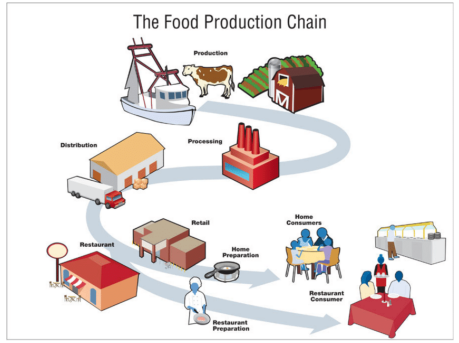


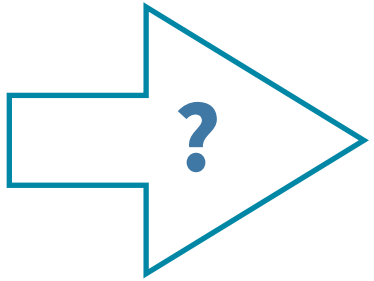
Events...

GPS coordinates

Temp sensor

Paperwork

Log DB



Why is the truck late?

Are the tomatoes still fresh?

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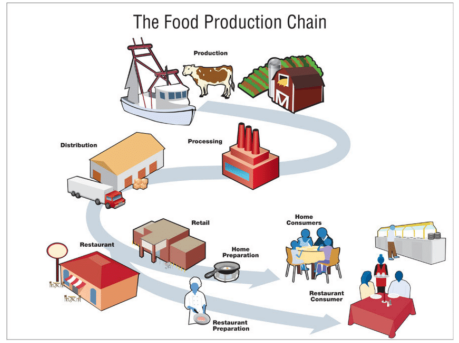

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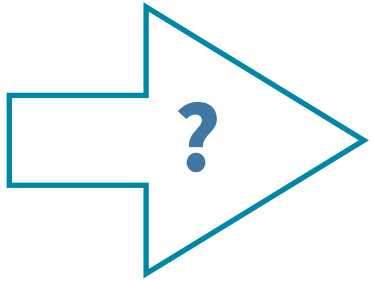

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Why this is hard

Incomplete/noisy/erroneous data

Need domain knowledge (“fresh”?)

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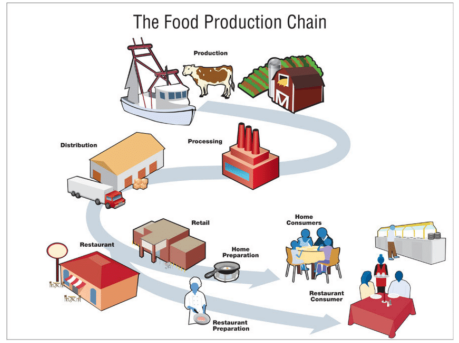

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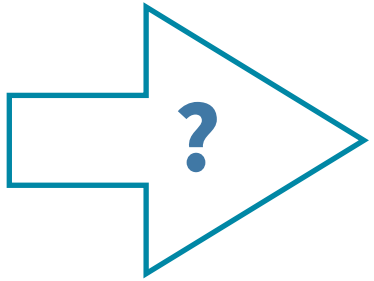

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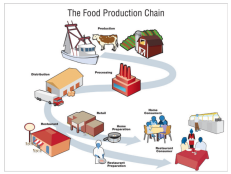

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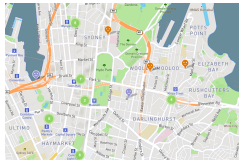

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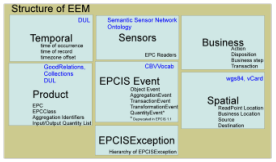

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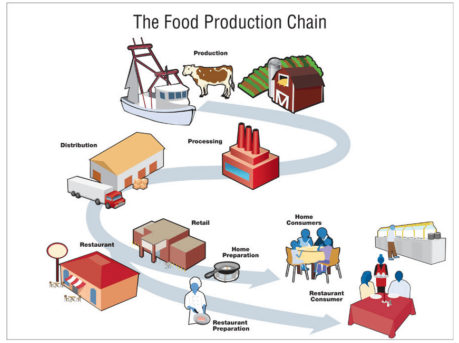

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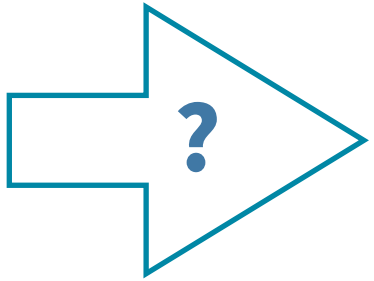

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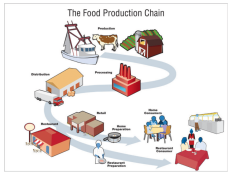
Domain *modelling* (first principles)

What-if *reasoning* and *explanations*



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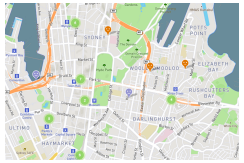

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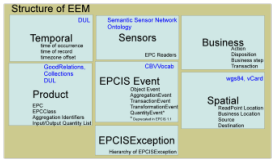

Stuck at warehouse / fresh

OR

Traffic jam / not fresh

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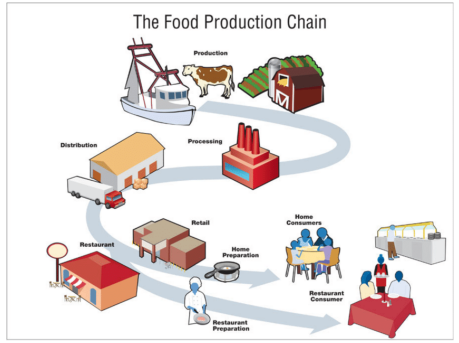

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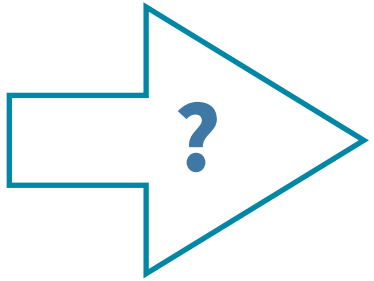

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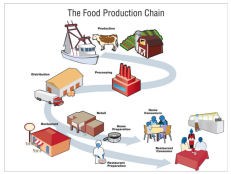

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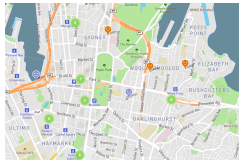

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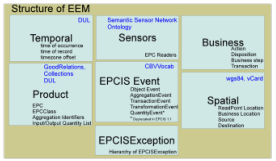

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Our *logic*-based approach

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Implemented in the Fusemate system

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Demo



Observation: truck is in Sydney at the warehouse

T

Demo



Observation: truck is in Sydney at the warehouse

T

Demo



Observation: tomatoes are loaded

T

Demo



Observation: tomatoes are loaded

T

Demo



Assumption as per schedule: truck is on the road

T

Demo



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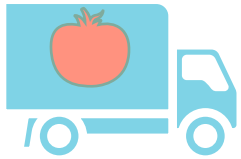


T **T+1**

Demo



Report: truck is on the road




T **T+1**

Demo

Report: truck is on the road

T **T+1** **T+2**

Demo

Conclusion: truck is on the road for too long - tomatoes are no longer fresh

T **T+1** **T+2**

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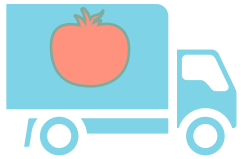
Report: actually, at T+1 truck was still in Sydney warehouse

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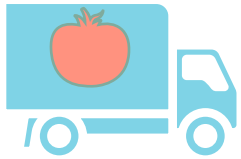


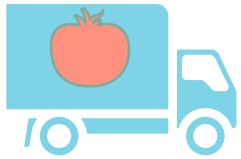
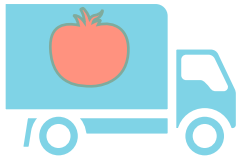



T **T+1** **T+2**

Demo



Conclusion: tomatoes are still fresh at T+2



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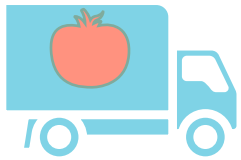
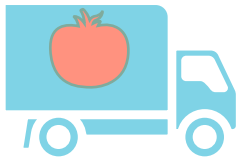
Conclusion: tomatoes are still fresh at T+2

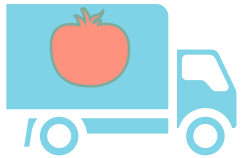


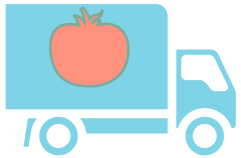
T **T+1** **T+2**

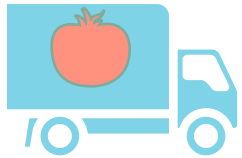
Demo



No information at T+3







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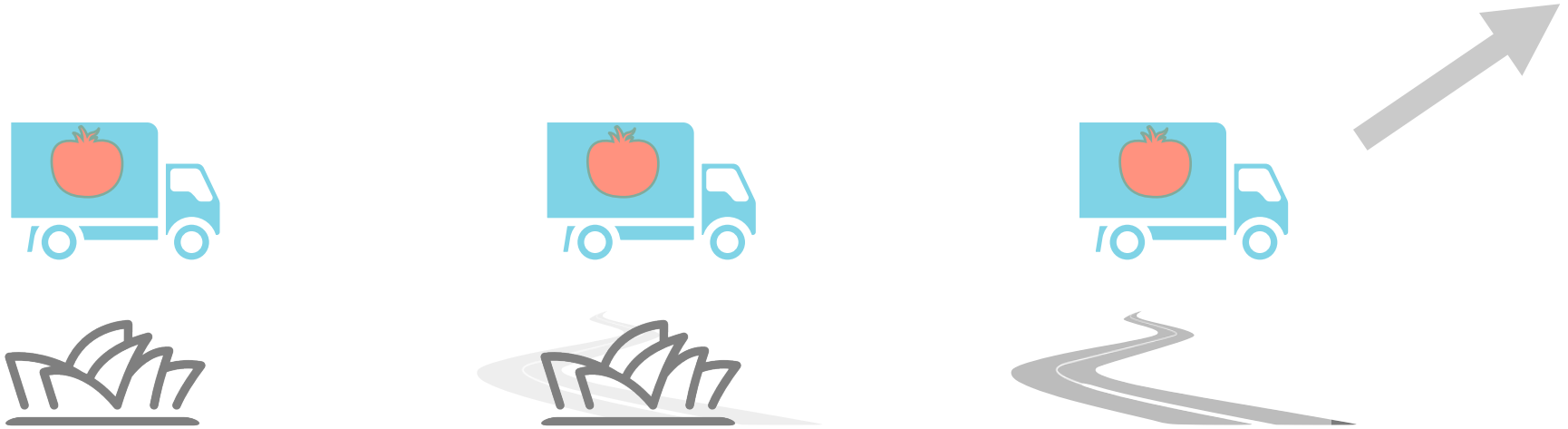
T+3: What if truck is on the road?



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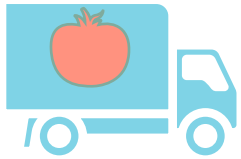
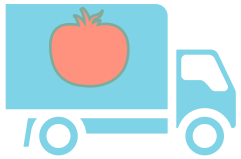
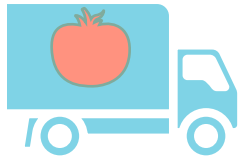


T **T+1** **T+2** **T+3**

Demo

T+3: What if truck is on the road? At Canberra warehouse?

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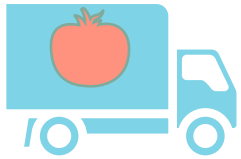
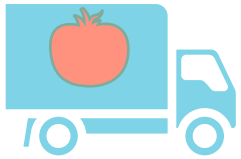
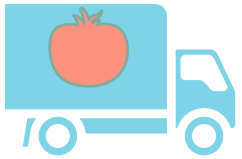
Demo



Report: truck at Canberra warehouse

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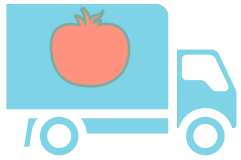
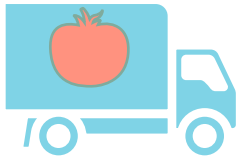
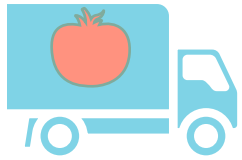





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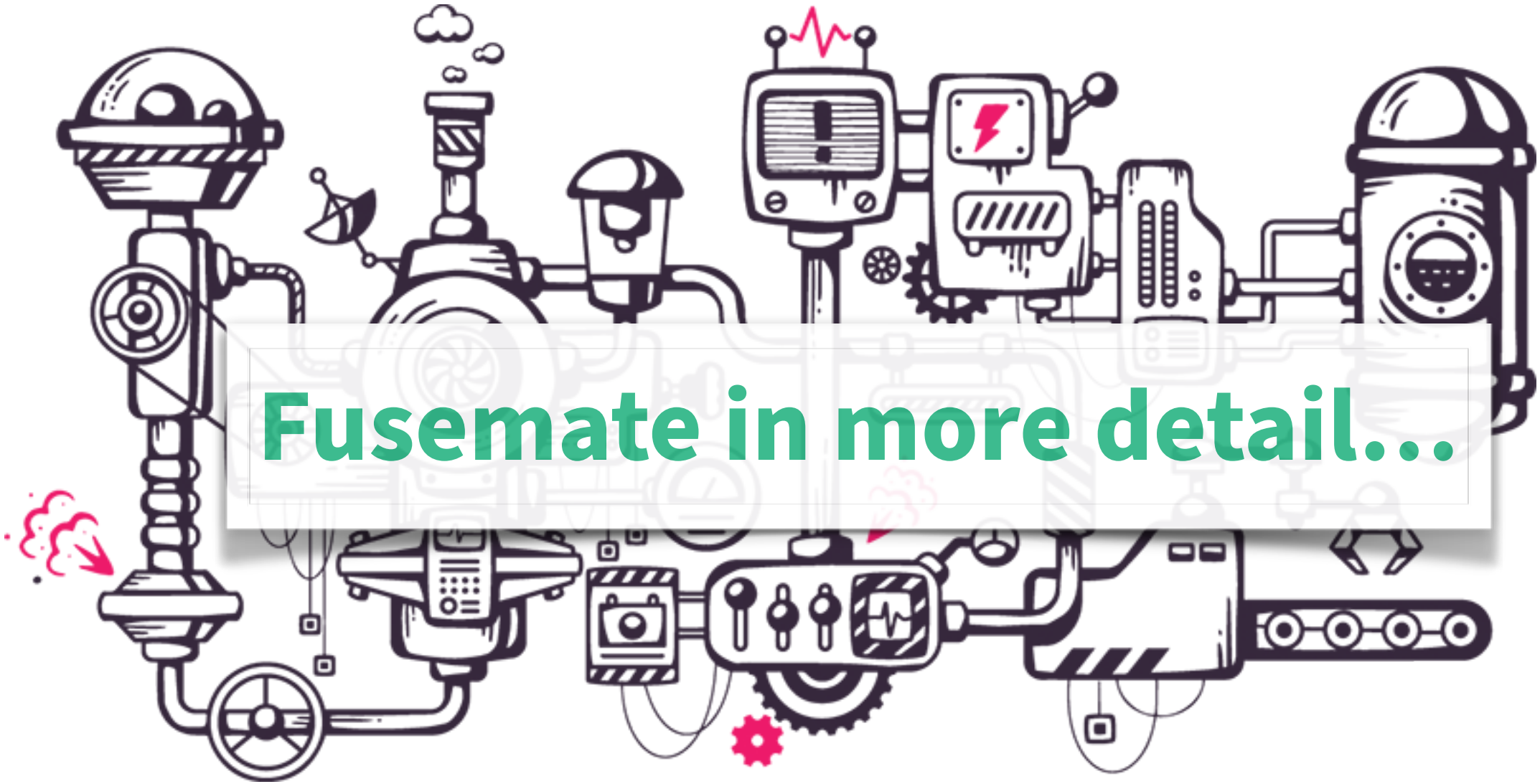


Fusemate in more detail...

Fusemate Model = If-Then Rules

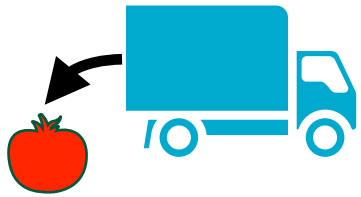
T1

T2

Time

Fusemate Model = If-Then Rules

T1



T1 < T ≤ T2

T2

NO!

Time

Fusemate Model = If-Then Rules

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If 

T1

and 

T1 < T ≤ T2

then 

T2

Time

Fusemate Model = If-Then Rules

If  and 

then 

T1 $T1 < T \leq T2$ T2

Time

If in(T1, B, C) **&** T1 < T2 **NOT exists** T **s.th.** T1 < T ≤ T2 **&** unload(T, B, C) **then** in(T2, B, C)

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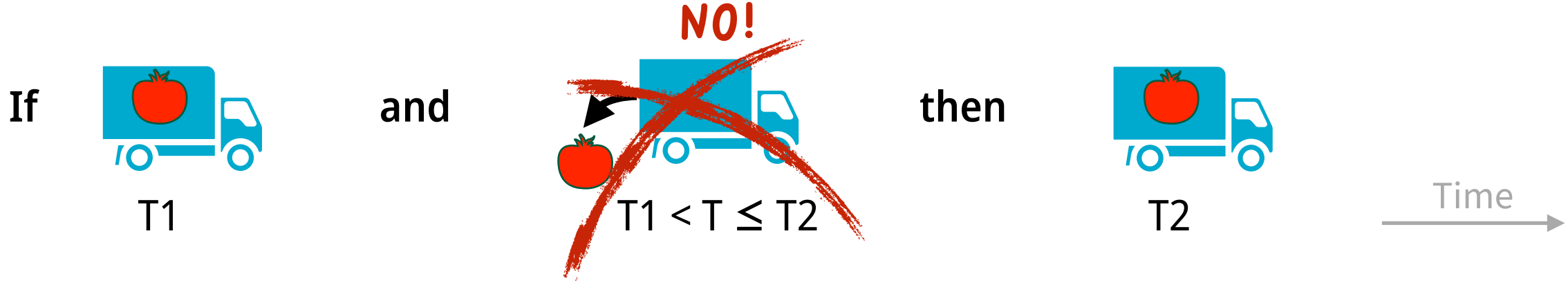

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default reasoning: "not known" (≠ "known not")

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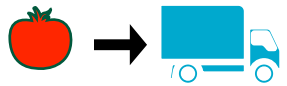
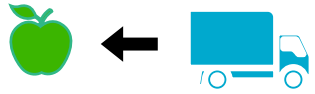
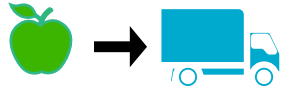
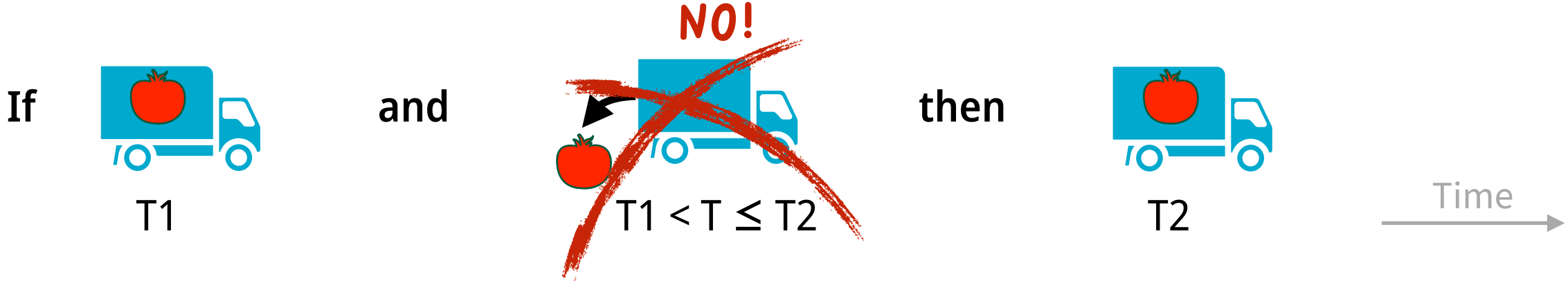
If  at T1 **and**  at T2 **then**

revise:  **or revise:** 

Fusemate Model = If-Then Rules



If in(T1, B, C) **&** T1 < T2 **NOT exists** T **s.th.** T1 < T ≤ T2 **&** unload(T, B, C) **then** in(T2, B, C)

default reasoning: "not known" (≠ "known not")

If → at T1 **and** ← at T2 **then**

revise: → **or revise:** ←

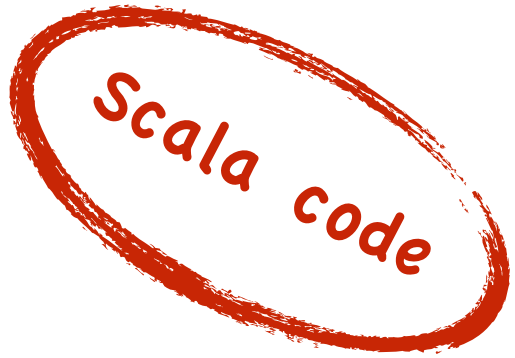
A model is a set of if-then rules plus …

Model = If-Then Rules + Scala Class Hierarchy

```
abstract class Item { val perishable: Boolean }
abstract class Fruit extends Item { val perishable = true }

abstract class Vehicle { val speed: Int }

case class Truck(id: Int, time: DateTime, load: Set[Item]) extends  Vehicle with LogicFact {
  val speed = 80
  val rules = List(
        Truck(id, t, load - item) :- Unload(id, t, item), ... )
  def hasPerishableLoad = load contains { _.perishable = true }
}
```



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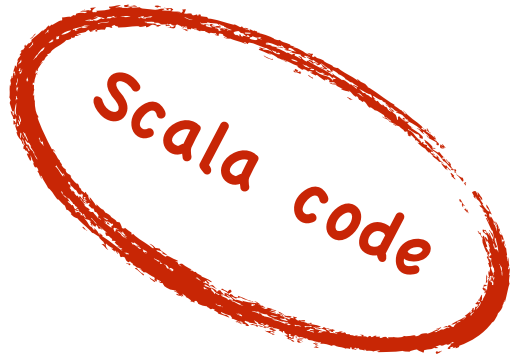

If-then rule extension

Model = If-Then Rules + Scala Class Hierarchy

```
case class Truck(id: Int, time: DateTime, load: Set[Item]) ... {
  ...
  @rules(id, time, load)
  val rules = List(
    Fail :-
      Unload(id, time, item),
      IF (! load contains items)

    Truck(id, next, load - item) :-
      Step(next, time),
      Unload(id, time, item),
      NOT(t < time, Unload(id, t, item) )
  )
}
```

Model = If-Then Rules + Scala Class Hierarchy

Scala library "set"

```
case class Truck(id: Int, time: DateTime, load: Set[Item]) ... {
  ...
  @rules(id, time, load)
  val rules = List(
    Fail :-
      Unload(id, time, item),
      IF (! load contains items)

    Truck(id, next, load - item) :-
      Step(next, time),
      Unload(id, time, item),
      NOT(t < time, Unload(id, t, item) )
  )
}
```

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Model = If-Then Rules + Scala Class Hierarchy

Scala library "set"

```
case class Truck(id: Int, time: DateTime, load: Set[Item]) ... {
  ...
  @rules(id, time, load)
  val rules = List(
    Fail :-
      Unload(id, time, item),
      IF (! load contains items)

    Truck(id, next, load - item) :-
      Step(next, time),
      Unload(id, time, item),
      NOT(t < time, Unload(id, t, item) )
  )
}
```

Macro annotation

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Model = If-Then Rules + Scala Class Hierarchy

Scala library "set"

```
case class Truck(id: Int, time: DateTime, load: Set[Item]) ... {
  ...
  @rules(id, time, load)
  val rules = List(
    Fail :-
      Unload(id, time, item),
      IF (! load contains items)

    Truck(id, next, load - item) :-
      Step(next, time),
      Unload(id, time, item),
      NOT(t < time, Unload(id, t, item) )
  )
}
```

Macro annotation

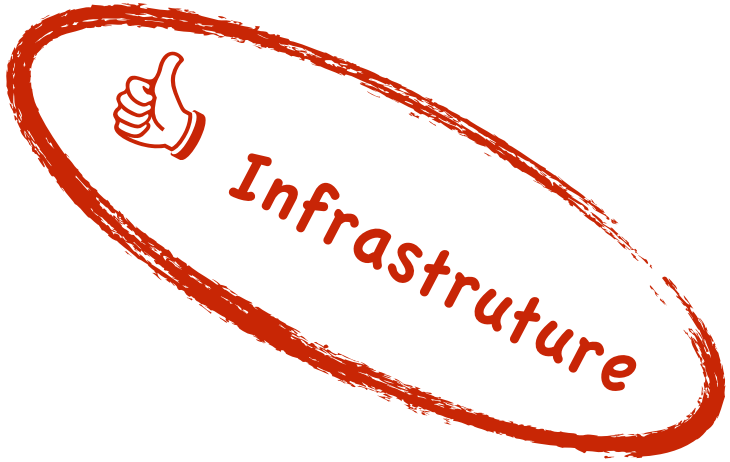
Expansion

```
case (Step(next, time1), Unload(id1, time2, item)) if
  time1 == time && time2 == time && id1 == id
  ! (model exists {
      case Unload(id2, t, item1) if id2 == id &&
                    t < time && item1 == item => true
      case _ => false
    }
  }) => Truck(id, next, load - item)
```

Modelling Paradigm Summary

Rules

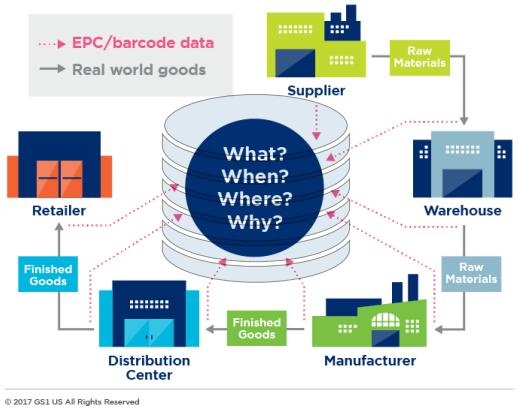
- **Inferences** on basis of incomplete information
- Derive **multiple** plausible explanations
- **Fix** erroneous event data and revise explanations



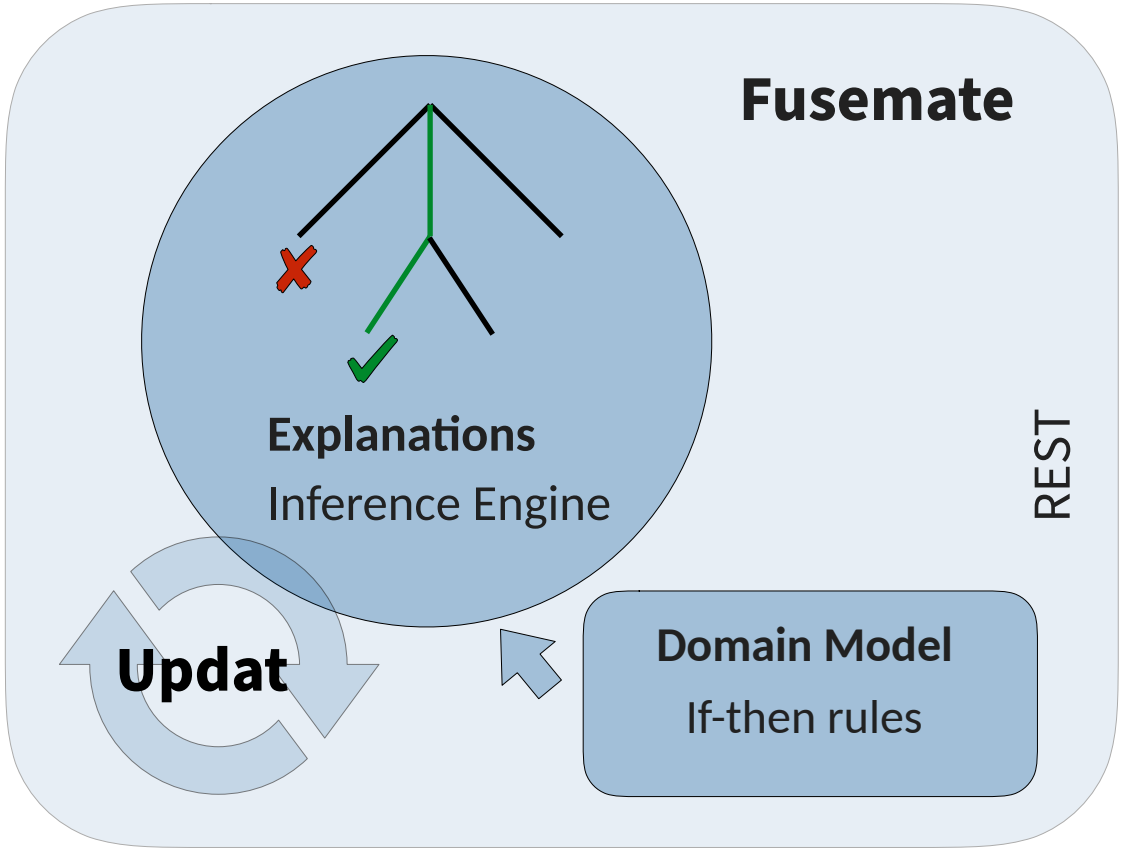
Scala

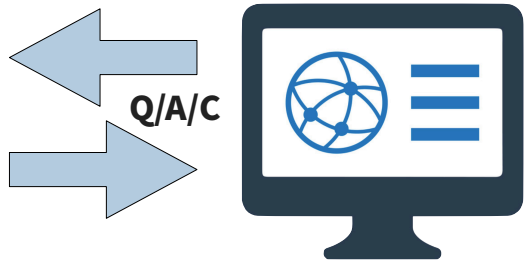
- **Rich data structures**
- **Java connectivity**
- **Inference engine**

System Architecture



EPCIS Events





Domain Model - e.g., *If item I is unpacked from a container C at time T then I must have been packed into C at some time S < T*

EPCIS Events - EPCIS events are sent to fusemate as they become available

Explanations - The inference engine derives a set of plausible models consistent with the EPCIS events so far

Q/A/C - *Where was item I at time T? Item I was unpacked from container C at time T and loc L. Item I has never arrived at L!*

Update - Plausible models are updated on every new EPCIS event and command provided by user

Case Study

Case Study - Deer Supply Chain

2013

The Use of EPC RFID Standards for Livestock and Meat Traceability

The New Zealand RFID Pathfinder Group

Gary Hartley
New Zealand RFID Pathfinder Group
January 2013

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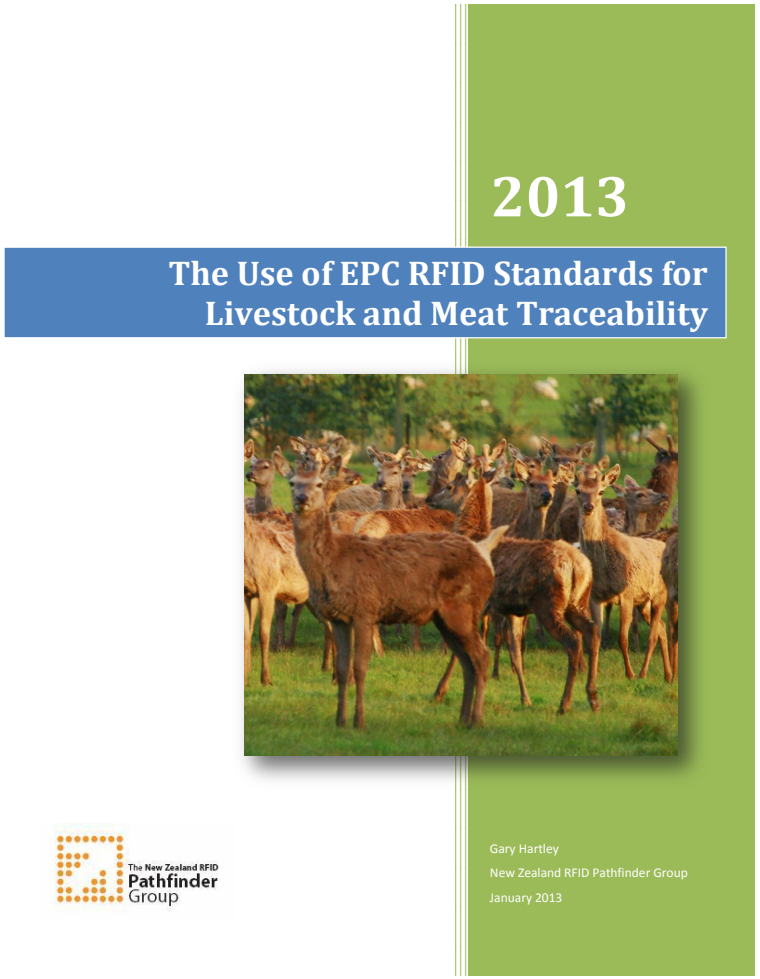
Case Study - Deer Supply Chain



12 events - from farm (NZ) to retailer (DE) encoded in EPCIS

Case Study - Deer Supply Chain

2013

The Use of EPC RFID Standards for Livestock and Meat Traceability

The New Zealand RFID Pathfinder Group

Gary Hartley
New Zealand RFID Pathfinder Group
January 2013

Process Step 4 - Animals arrive at Mountain River Processors' stun box

Figure 5.7 - Stun Box

Figure 5.8 - RFID reader at Stun Box

Figure 5.7 illustrates animals in the location of the stun box. Note the RFID ear tags in the ears of the animals. Figure 5.8 illustrates the RFID antenna setup at the stun box.

Process Step 5 - Cartons of finished Venison cuts packed into cartons at Mountain River processor and moved from the boning room into chiller room

Figure 5.9 - UHF RFID tags used on cartons

Figure 5.10 - UHF RFID tags positioned on cartons

Figure 5.11 – Tagged cartons moving from boning room to chiller room

Figure 5.9, Figure 5.10 and Figure 5.11 illustrate the affixing of EPC UHF RFID tags on the cartons in the boning room and moving of cartons of finished venison cuts into the chiller room in preparation for loading the shipping container.

7

12 events - from farm (NZ) to retailer (DE) encoded in EPCIS

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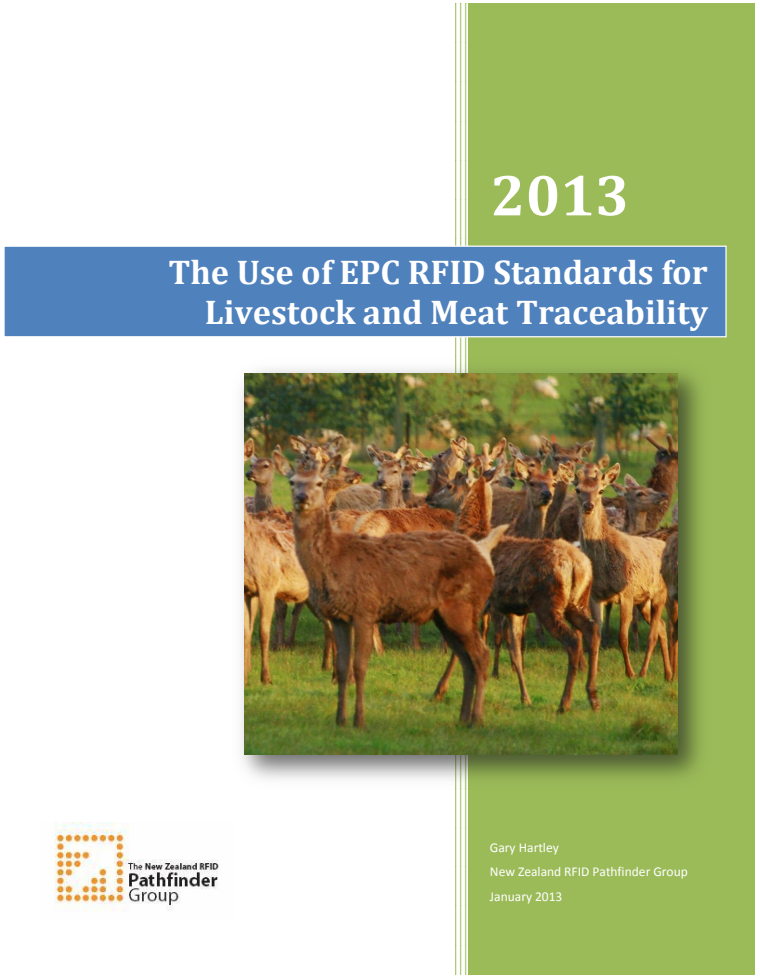
Case Study - Deer Supply Chain



Process Step 4 - Animals

Figure 5.7 - S

Figure 5.7 illustrates anima
animals. Figure 5.8 illustrat

Process Step 5 - Cartons
processor and moved fro

Figure 5.9 - UHF RFID ta
used on cartons

Figure 5.9, Figure 5.10 and
in the boning room and mo
for loading the shipping con

EPCIS Event Details

Event Time	16/10/2012 11:54:38 +1300
Timezone Offset	+13:00
Event Type	ObjectEvent
Action	ADD
EPC	urn:epc:id:sgtin:9421900217.003.1073742106 urn:epc:id:sgtin:9421900217.003.1073742107 urn:epc:id:sgtin:9421900217.003.1073742109 urn:epc:id:sgtin:9421900217.003.1073742110 urn:epc:id:sgtin:9421900217.003.1073742111 urn:epc:id:sgtin:9421900217.003.1073742112 urn:epc:id:sgtin:9421900217.003.1073742113 urn:epc:id:sgtin:9421900217.003.1073742114 urn:epc:id:sgtin:9421900217.003.1073742115 urn:epc:id:sgtin:9421900217.003.1073742116 urn:epc:id:sgtin:9421900217.003.1073742117 urn:epc:id:sgtin:9421900217.003.1073742118 urn:epc:id:sgtin:9421900217.003.1073742119 urn:epc:id:sgtin:9421900217.003.1073742120 urn:epc:id:sgtin:9421900217.003.1073742121 urn:epc:id:sgtin:9421900217.003.1073742122 urn:epc:id:sgtin:9421900217.003.1073742123 urn:epc:id:sgtin:9421900217.003.1073742124 urn:epc:id:sgtin:9421900217.003.1073742126 urn:epc:id:sgtin:9421900217.003.1073742127
BizStep	urn:epcglobal:cbv:bizstep:commissioning
Disposition	urn:epcglobal:cbv:disp:active
BizLocation	urn:epc:id:sgln:942900.009772.ON_FARM
Read Point	urn:epc:id:sgln:942900.009772.DEER_CRUSH

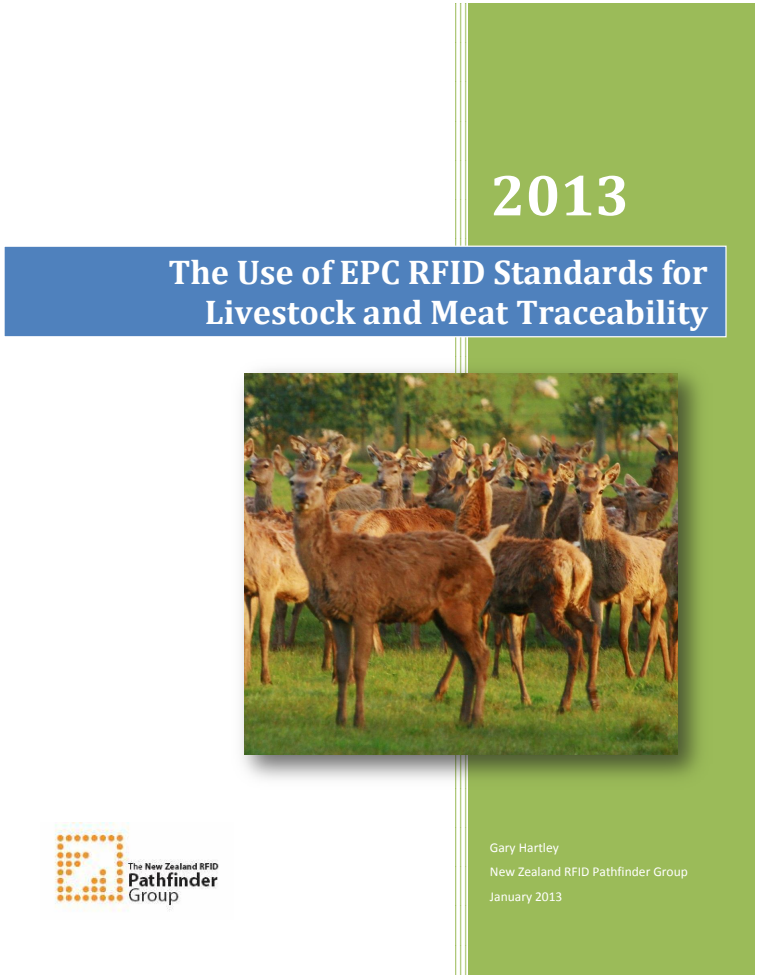
Table 6.3 - Commissioning event - tagging of animals

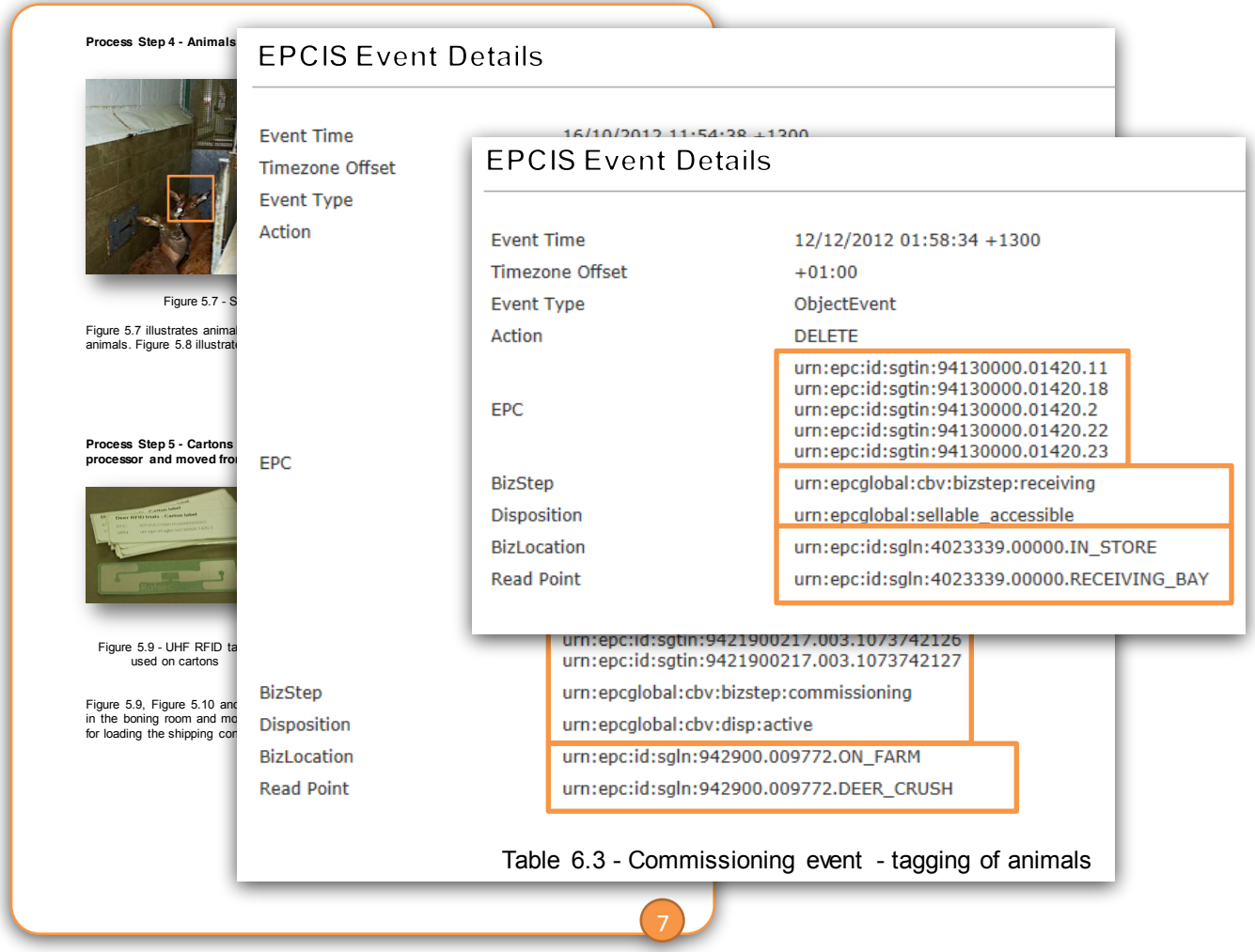
7

12 events - from farm (NZ) to retailer (DE) encoded in EPCIS

CSIRO DATA 61

Case Study - Deer Supply Chain





12 events - from farm (NZ) to retailer (DE) encoded in EPCIS

Case Study - WWWW

EPCIS defines lower-level events and higher-level “WWWW” concepts

WWWW - What? Where? When? Why?

Carton-2
MountainRiverProcessors/NewZealand/BONING_ROOM_EXIT
MountainRiverProcessors/NewZealand/CHILLER_ROOM
commissioning - active
Add
2012-10-25T11:25:53+13:00

Case Study - WWWW

EPCIS defines lower-level events and higher-level “WWWW” concepts

WWWW - What? Where? When? Why?

Carton-2
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What

Case Study - WWWW

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commissioning - active
Add
2012-10-25T11:25:53+13:00

What

Where - Read point

Case Study - WWWW

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commissioning - active
Add
2012-10-25T11:25:53+13:00

What

Where - Read point

Where - Biz location

Case Study - WWWW

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commissioning - active
Add
2012-10-25T11:25:53+13:00

What
Where - Read point
Where - Biz location
Why - Biz step - Disposition

Case Study - WWWW

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Case Study - WWWW

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Case Study - WWWW

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MountainRiverProcessors/NewZealand/CHILLER_ROOM
commissioning - active
Add
2012-10-25T11:25:53+13:00

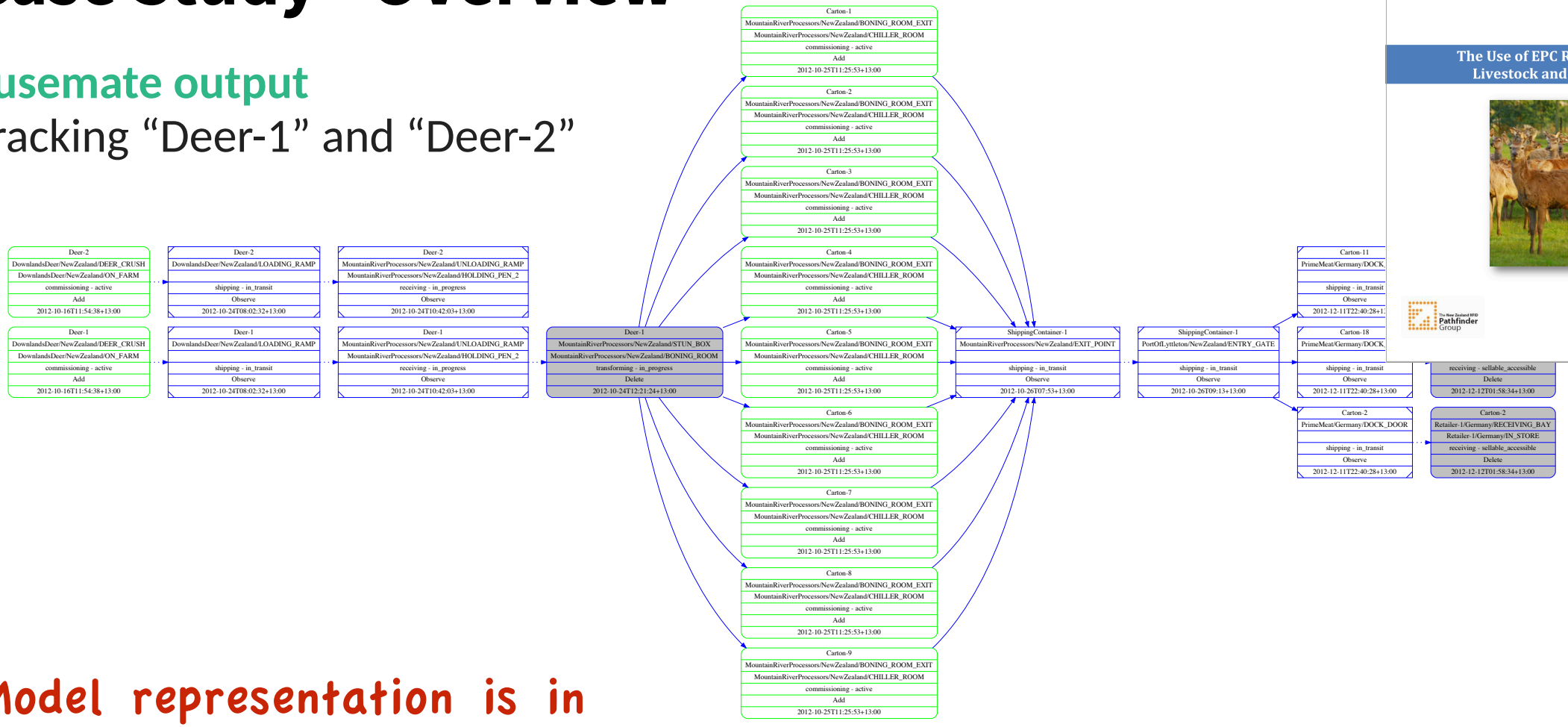
What
Where - Read point
Where - Biz location
Why - Biz step - Disposition
How
When

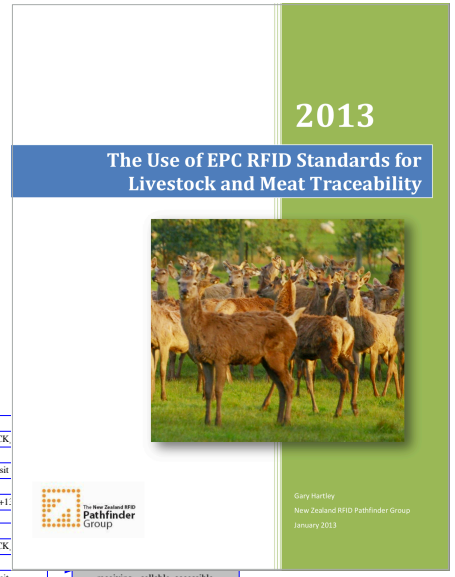
There are if-then rules for deriving **WWWW**s from EPCIS low-level events

Case Study - Overview

Fusemate output

Tracking “Deer-1” and “Deer-2”



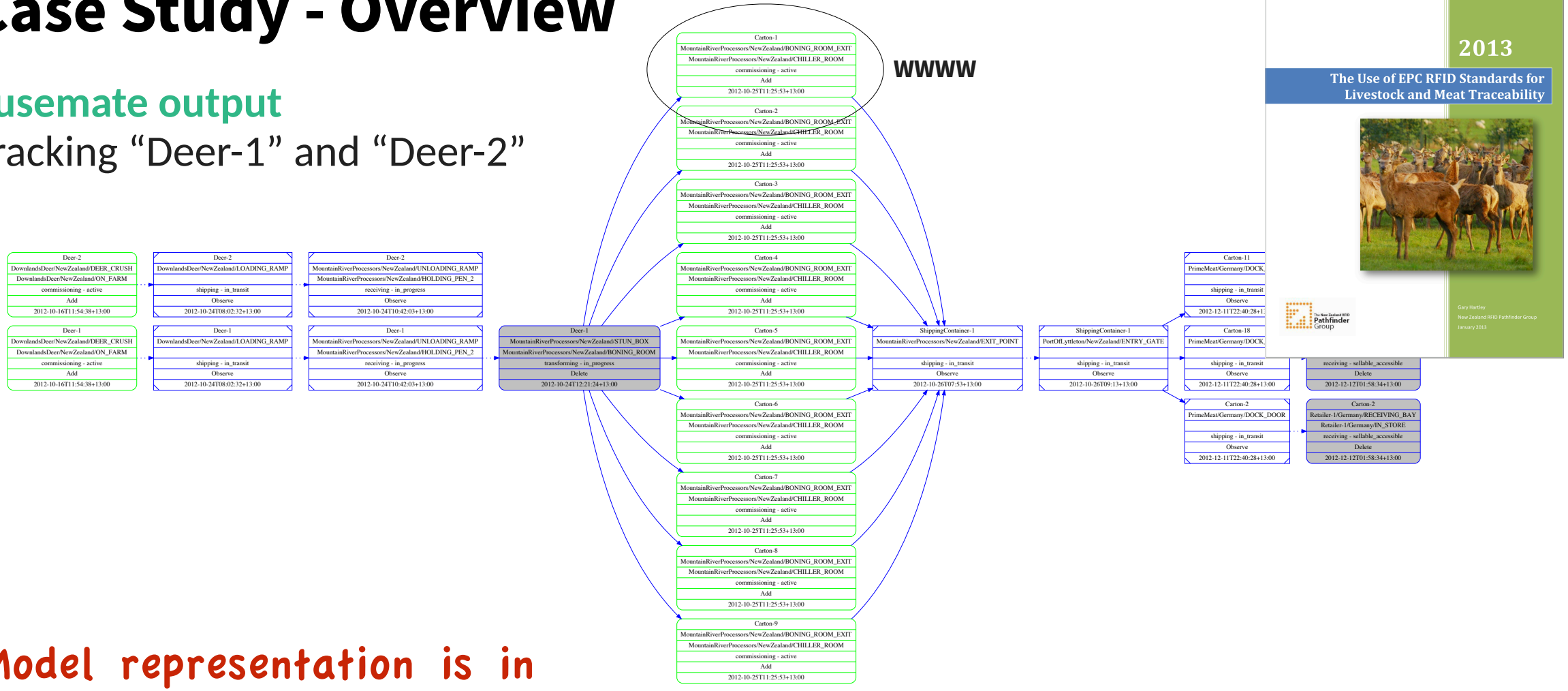


Model representation is in terms of WWWW, Aggregation and Association concepts

Case Study - Overview

Fusemate output

Tracking “Deer-1” and “Deer-2”



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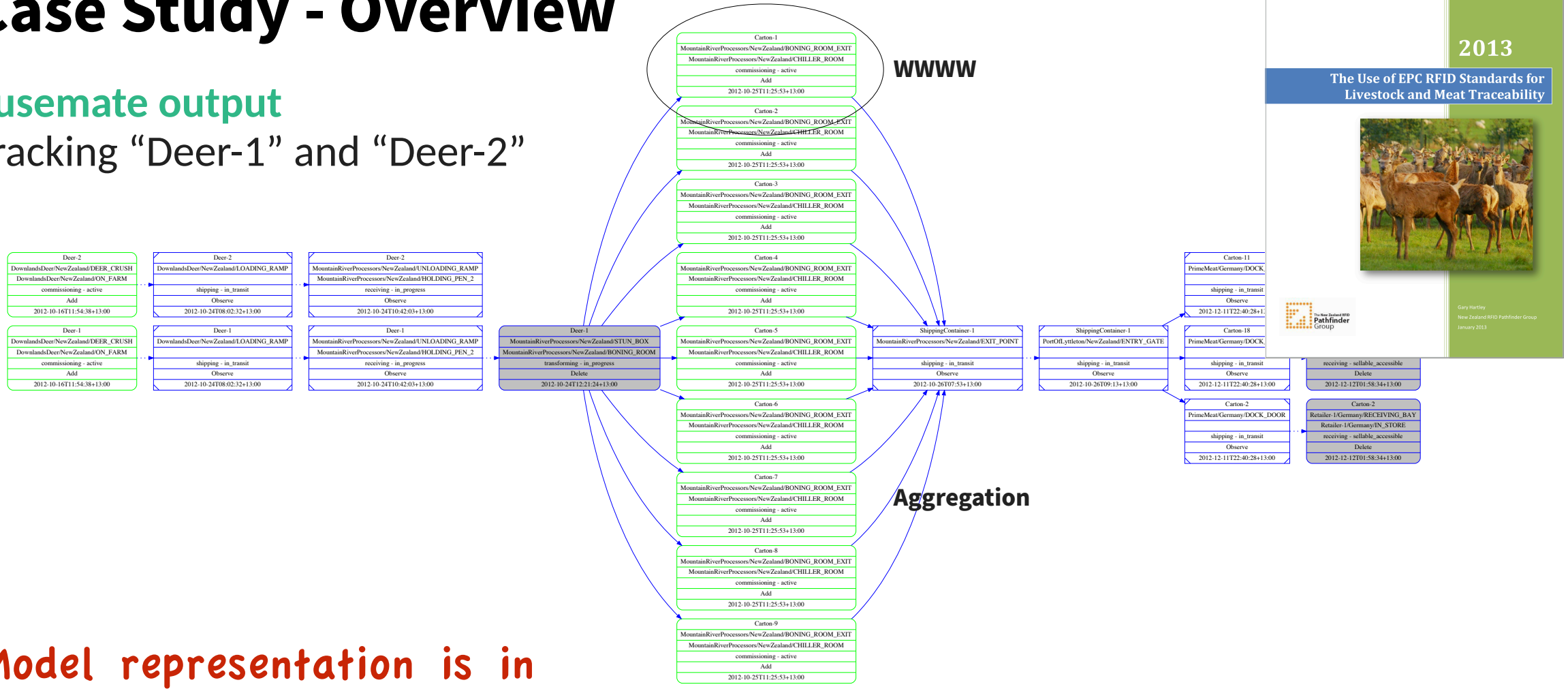
Case Study - Overview

Fusemate output

Tracking “Deer-1” and “Deer-2”



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Case Study - Overview

Fusemate output

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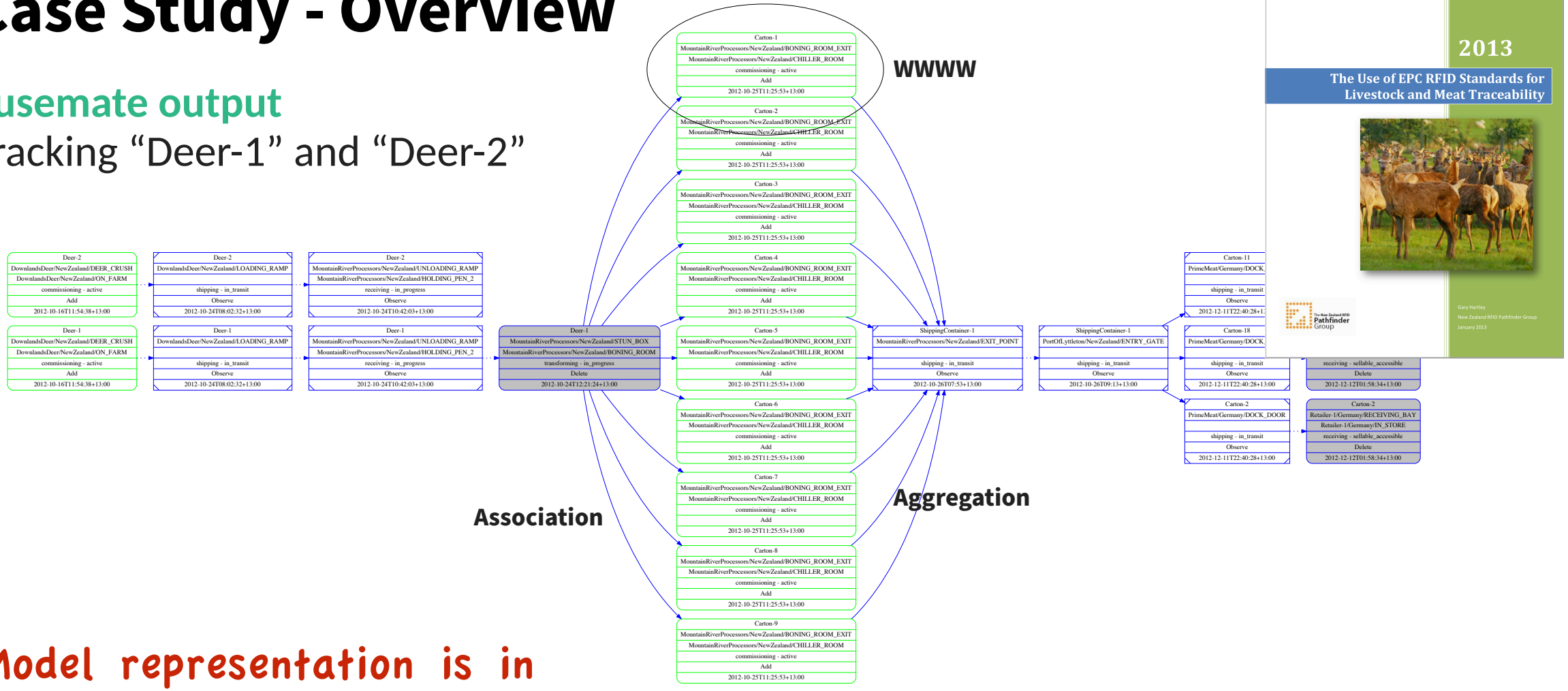

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Case Study - Overview

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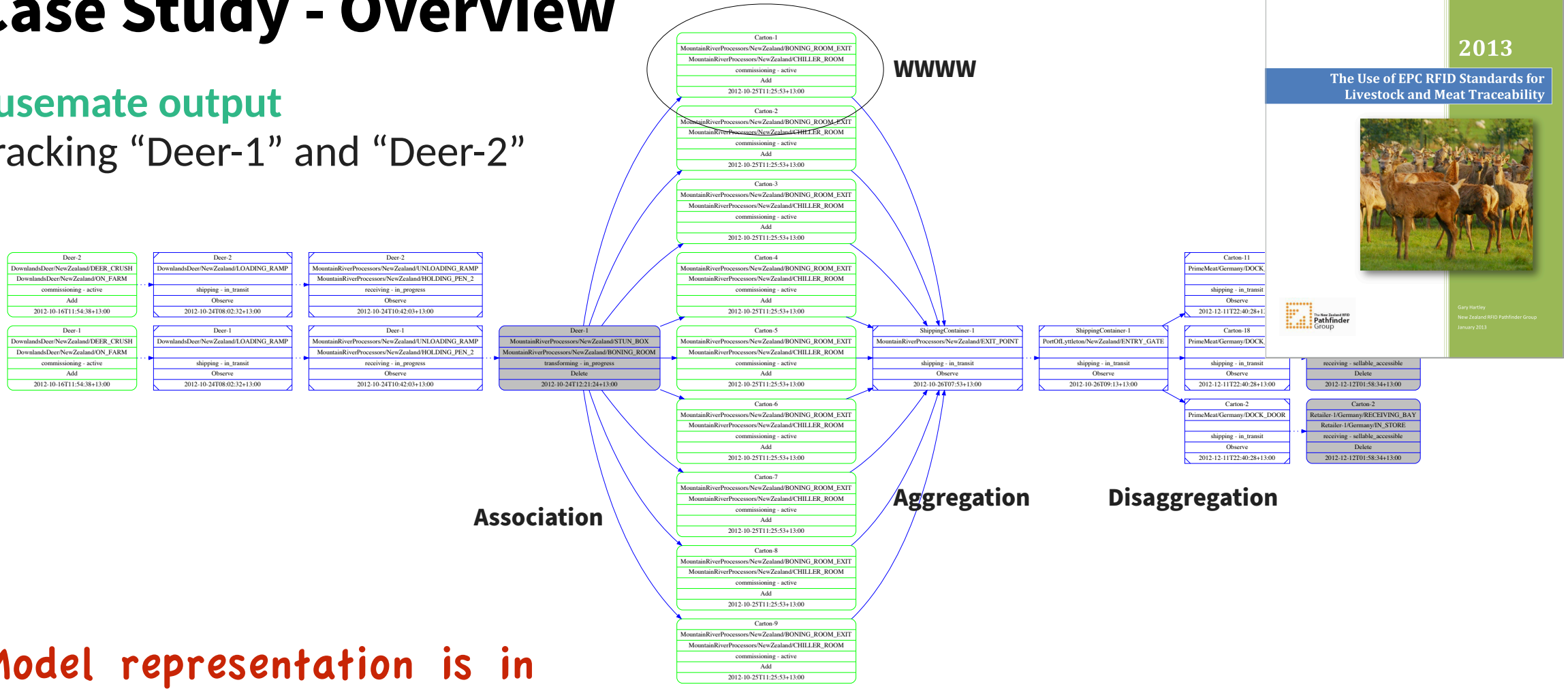
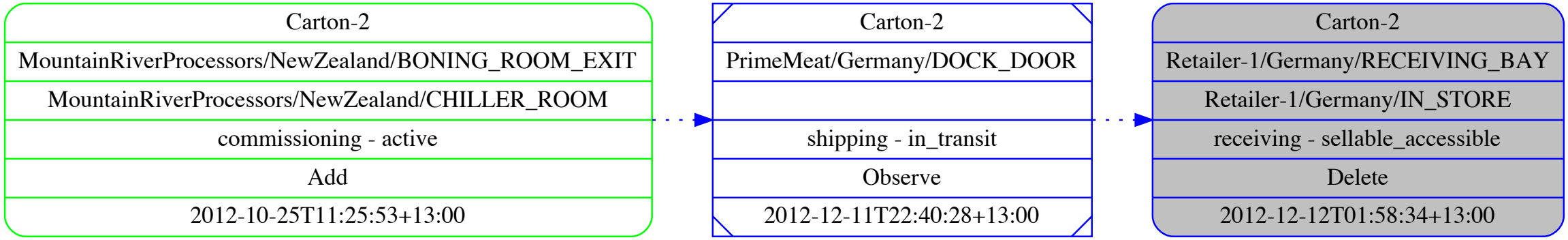
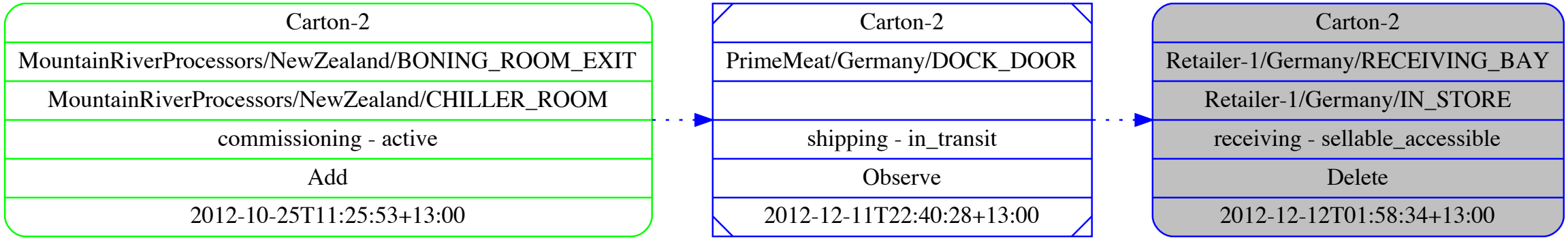


Model representation is in terms of WWWW, Aggregation and Association concepts

Modelling Experiment - Multiple Explanations

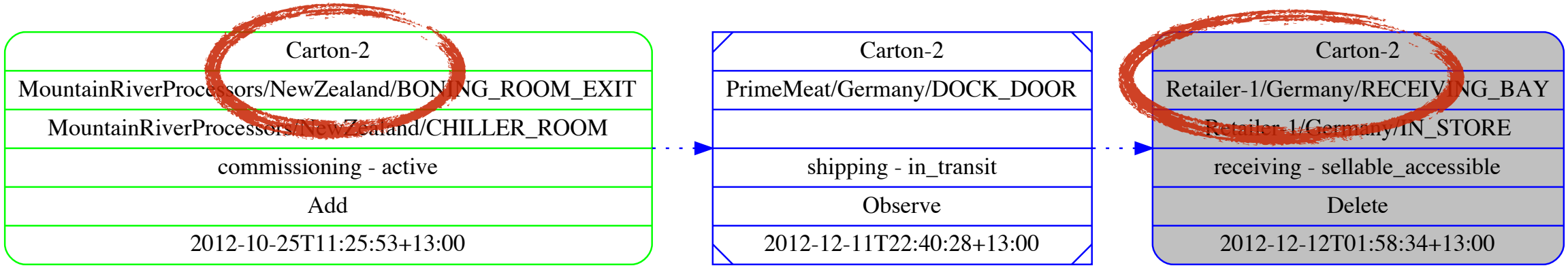


Modelling Experiment - Multiple Explanations



What is known

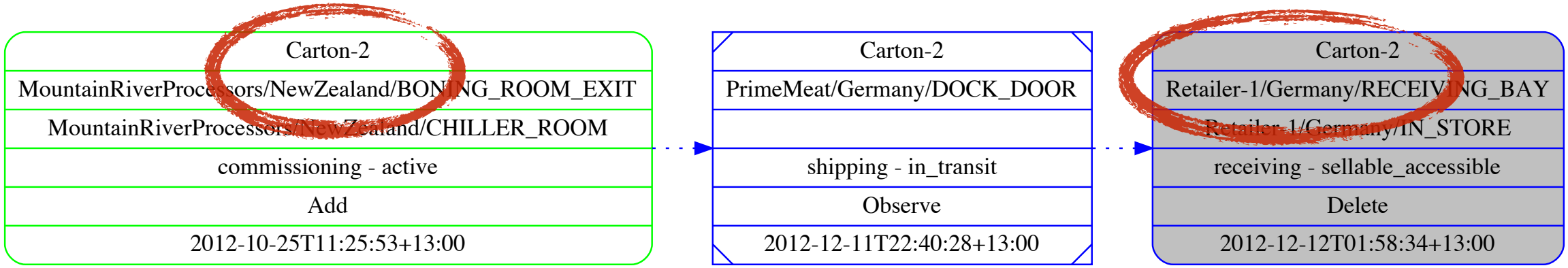
Modelling Experiment - Multiple Explanations



What is known

- Carton-2 has arrived at Retailer-1 in Germany

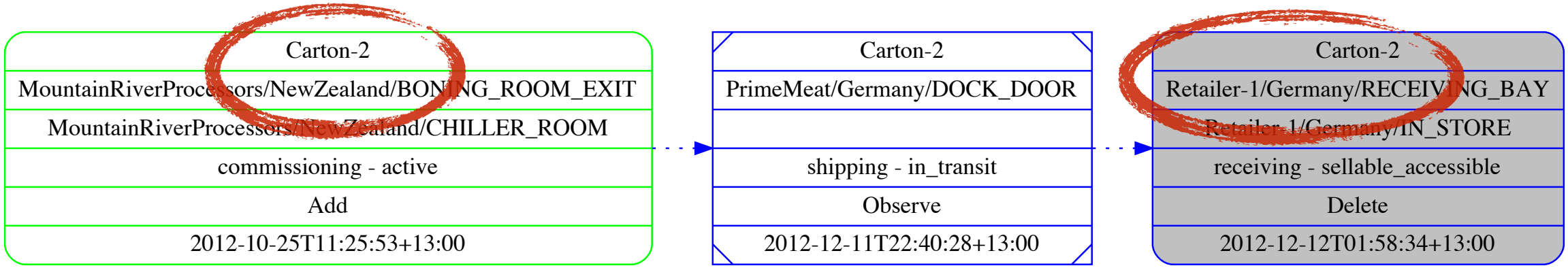
Modelling Experiment - Multiple Explanations



What is known

- Carton-2 has arrived at Retailer-1 in Germany
- Carton-13 was added to the supply chain like Carton-2 above

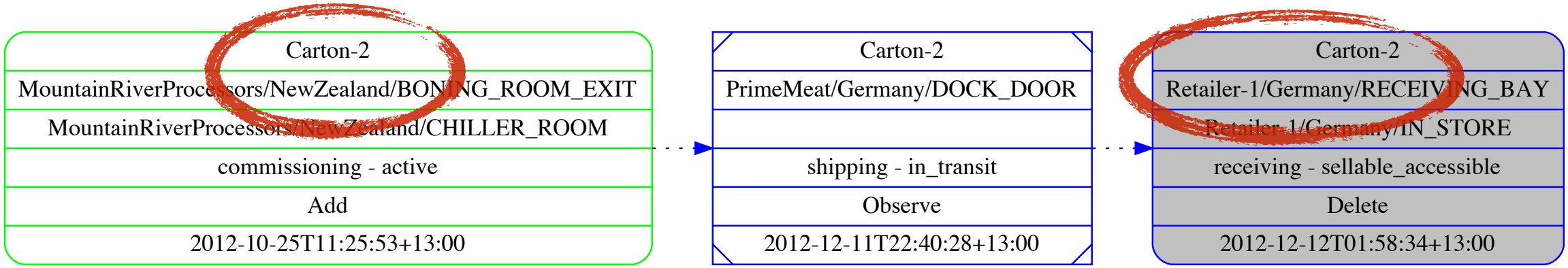
Modelling Experiment - Multiple Explanations



What is known

- Carton-2 has arrived at Retailer-1 in Germany
- Carton-13 was added to the supply chain like Carton-2 above
- Carton-13 leaves no trace but it should also have arrived at Retailer-1 in Germany

Modelling Experiment - Multiple Explanations



What is known

- Carton-2 has arrived at Retailer-1 in Germany
- Carton-13 was added to the supply chain like Carton-2 above
- Carton-13 leaves no trace but it should also have arrived at Retailer-1 in Germany

What went wrong?

Fusemate diagnosis scenario - Compute some plausible explanations

Modelling Experiment - Multiple Explanations

We start the diagnosis by telling Fusemate that Carton-13 behaves like Carton-2

```
trackByCopy("urn:epc:id:sgtin:94130000.01420.2", "urn:epc:id:sgtin:94130000.01420.13")
```

Result

Modelling Experiment - Multiple Explanations

We start the diagnosis by telling Fusemate that Carton-13 behaves like Carton-2

```
trackByCopy("urn:epc:id:sgtin:94130000.01421.2","urn:epc:id:sgtin:94130000.01420.13")
```

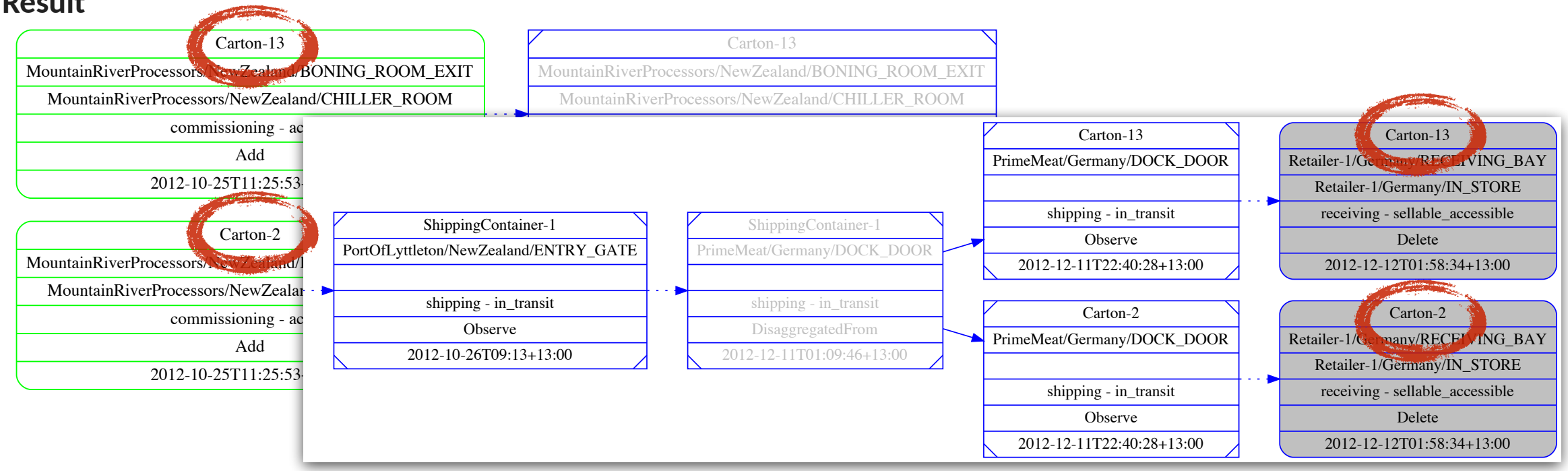
Result

Modelling Experiment - Multiple Explanations

We start the diagnosis by telling Fusemate that Carton-13 behaves like Carton-2

```
trackByCopy("urn:epc:id:sgtin:94130000.01421.2", "urn:epc:id:sgtin:94130000.01420.13")
```

Result

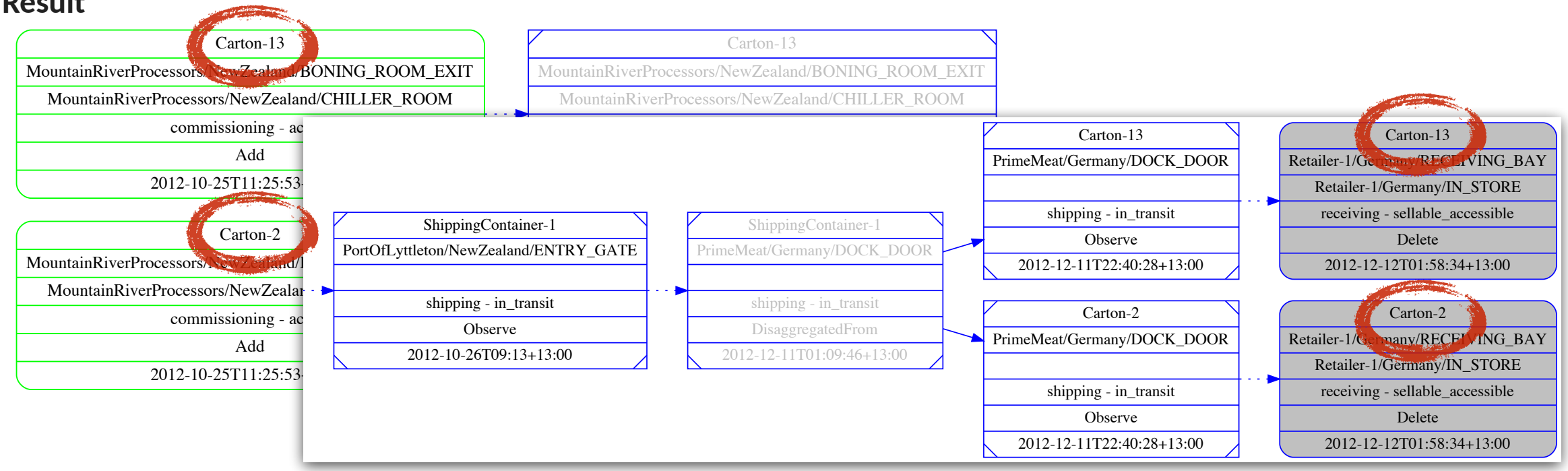


Modelling Experiment - Multiple Explanations

We start the diagnosis by telling Fusemate that Carton-13 behaves like Carton-2

```
trackByCopy("urn:epc:id:sgtin:94130000.01421.2","urn:epc:id:sgtin:94130000.01420.13")
```

Result



Now add knowledge of what (not) happened

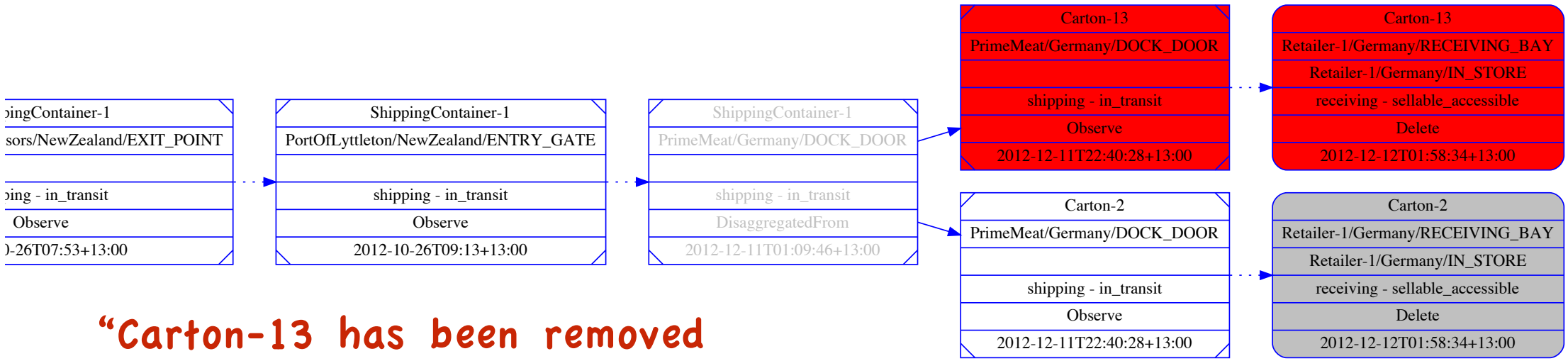
Modelling Experiment - Multiple Explanations

A phone call confirms that Carton-13 was not seen at the DOCK_DOOR any time after 11/12/2012:

This information is provided to Fusemate (details not shown here)

Plausible Explanation (1)

Negative conclusions = “known not”



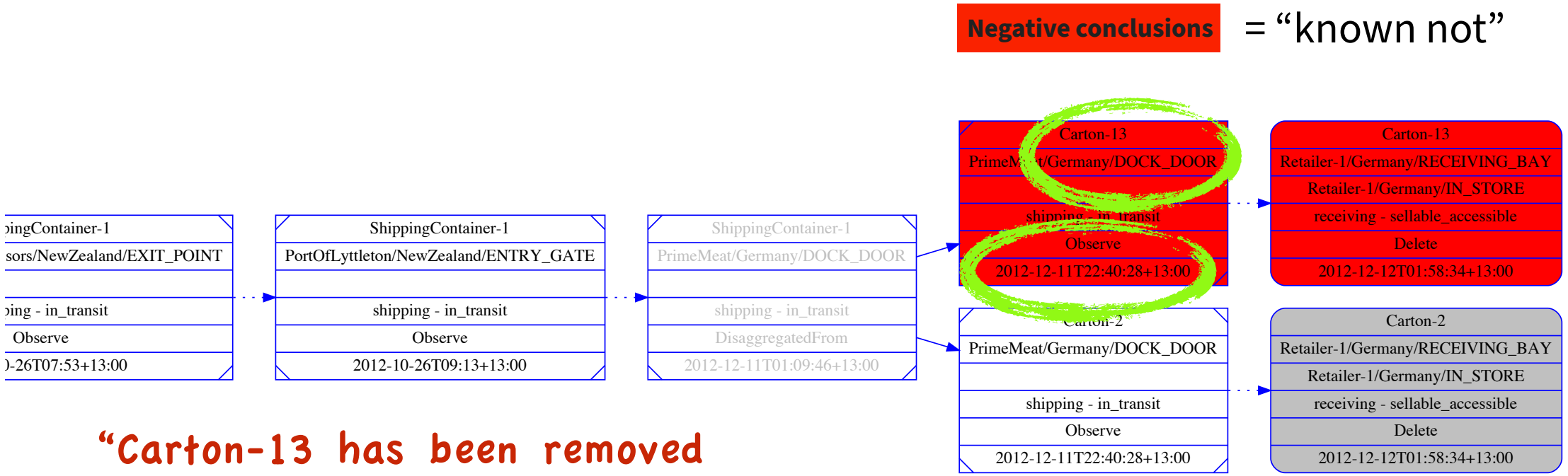
“Carton-13 has been removed from Container-1 but there is no trace from then on”

Modelling Experiment - Multiple Explanations

A phone call confirms that Carton-13 was not seen at the DOCK_DOOR any time after 11/12/2012:

This information is provided to Fusemate (details not shown here)

Plausible Explanation (1)



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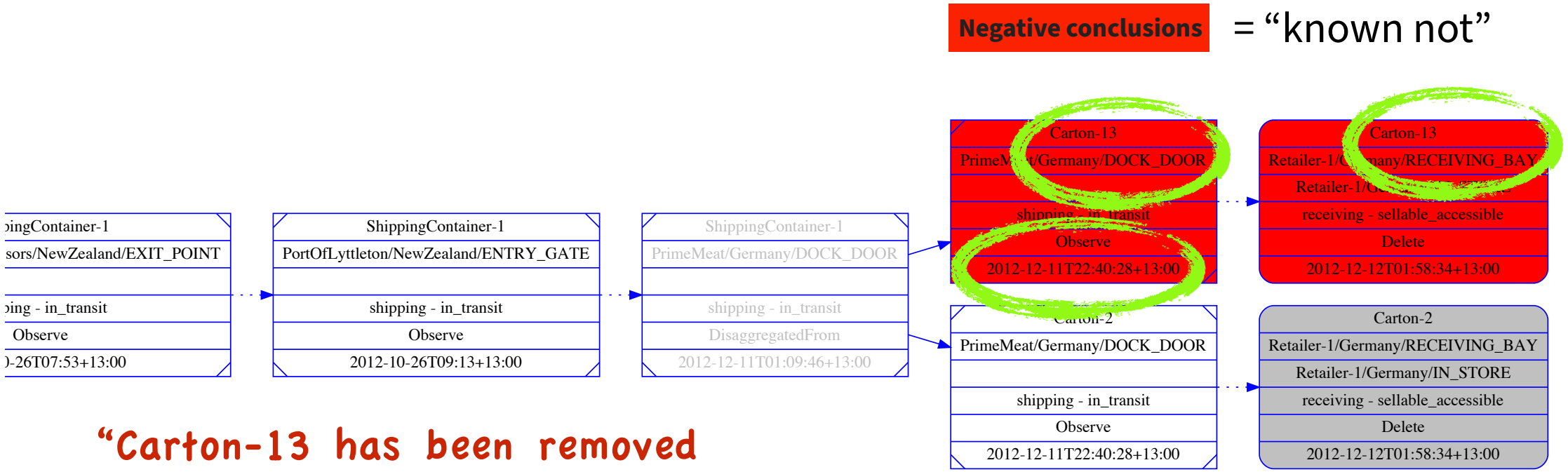
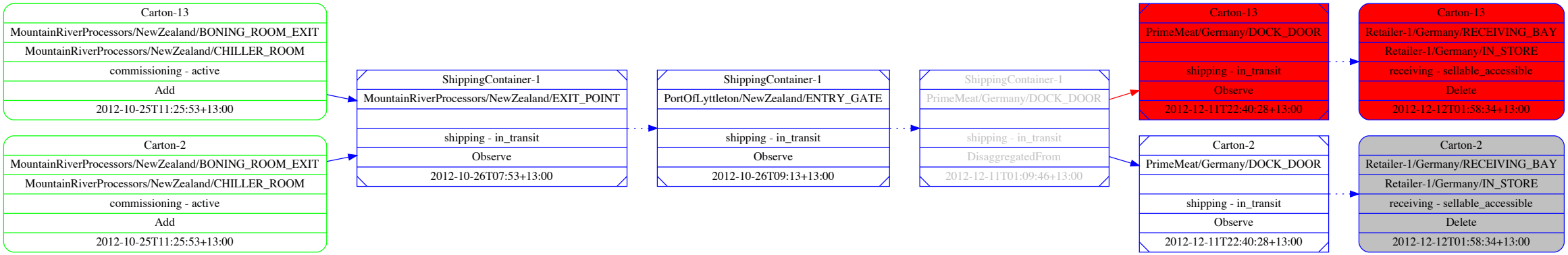


“Carton-13 has been removed from Container-1 but there is no trace from then on”

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (2)



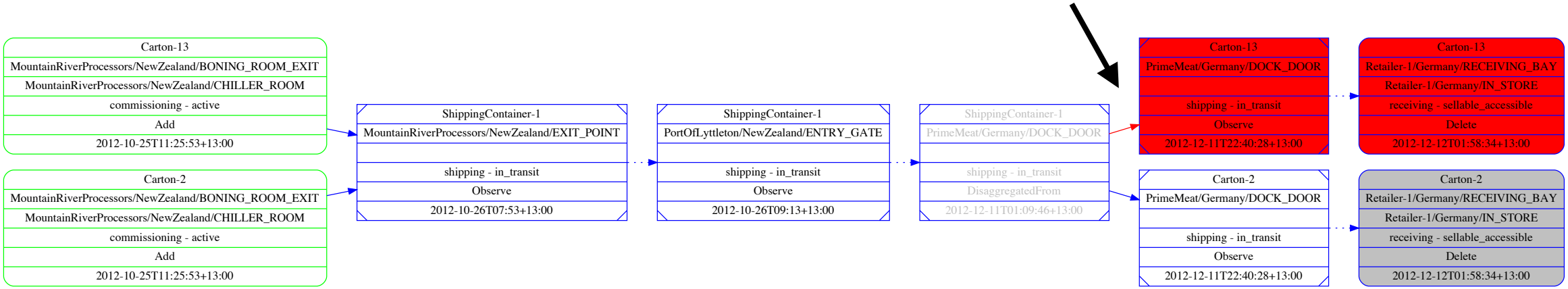
"Carton-13 has not been removed from Container-1 (still in the container?)"

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (2)

Arrow in red now

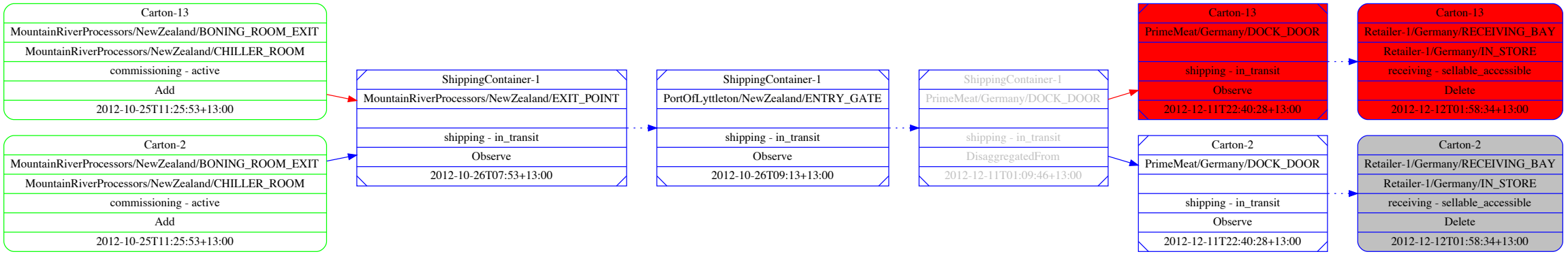


"Carton-13 has not been removed from Container-1 (still in the container?)"

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (3)



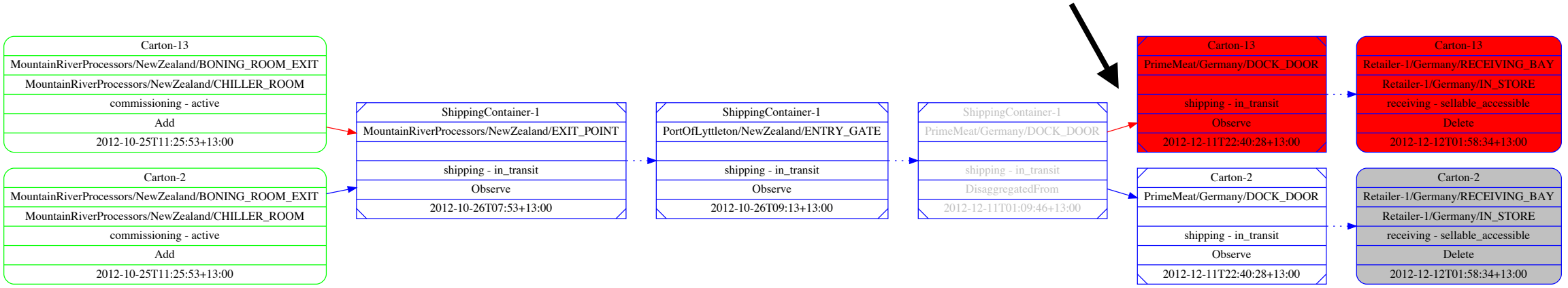
"Carton-13 was not loaded into Container-1 in the first place"

(And hence cannot be unloaded either as per rules)

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (3)



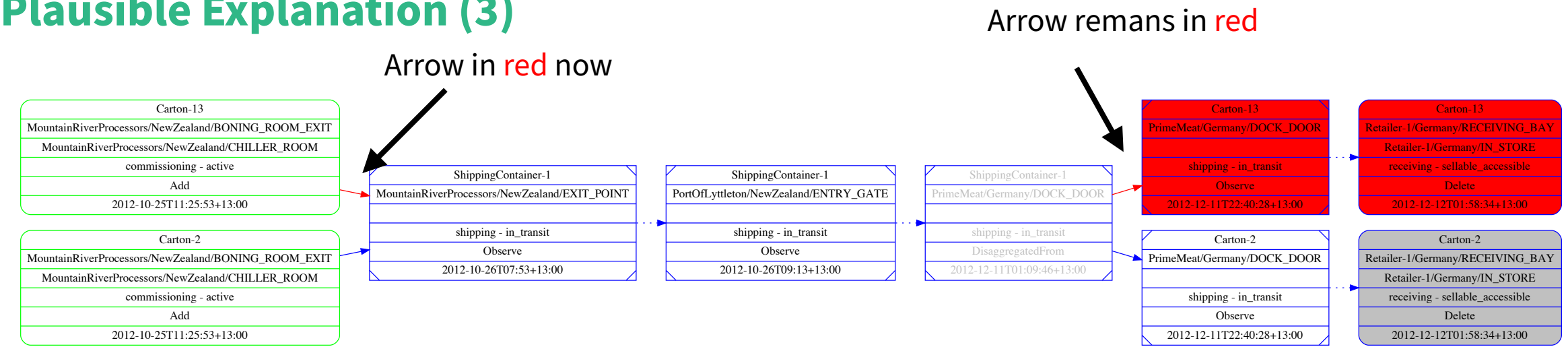
"Carton-13 was not loaded into Container-1 in the first place"

(And hence cannot be unloaded either as per rules)

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (3)



"Carton-13 was not loaded into Container-1 in the first place"

(And hence cannot be unloaded either as per rules)

Modelling Experiment - Multiple Explanations

The user asks the system to compute the next plausible model

Plausible Explanation (4)

N/A

In particular Fusemate does not generate:
"Carton-13 has been removed from the Container 1
but was not loaded earlier into Container 1"

User Interface - Under Development

```
OK
command read("demo/deer/data/event-05.xml")
OK
command read("demo/deer/data/event-06.xml")
OK
command read("demo/deer/data/event-07.xml")
OK
command read("demo/deer/data/event-08.xml")
OK
command read("demo/deer/data/event-09.xml")
OK
command read("demo/deer/data/event-10.xml")
```

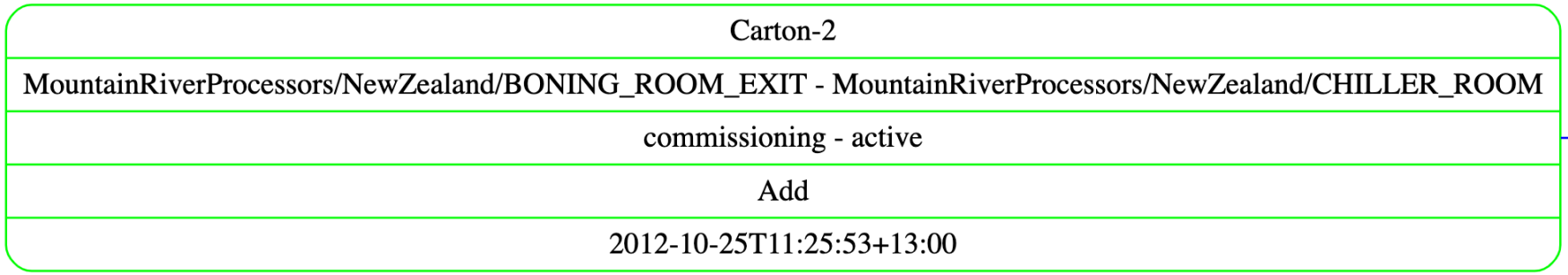
```
command track("urn:epc:id:sgtin:94130000.01420.2")

query currentModel filter { isAbout(_, "Carton-2") }

command toDotFile(currentModel, "demo/deer/out/client-tracking1.dot", display = true)

query toDot(currentModel)
```

Send Qu

0 1 2

Json | Json Diff | **Graph** | Map

Old Graph | New Graph



User Interface - Under Development

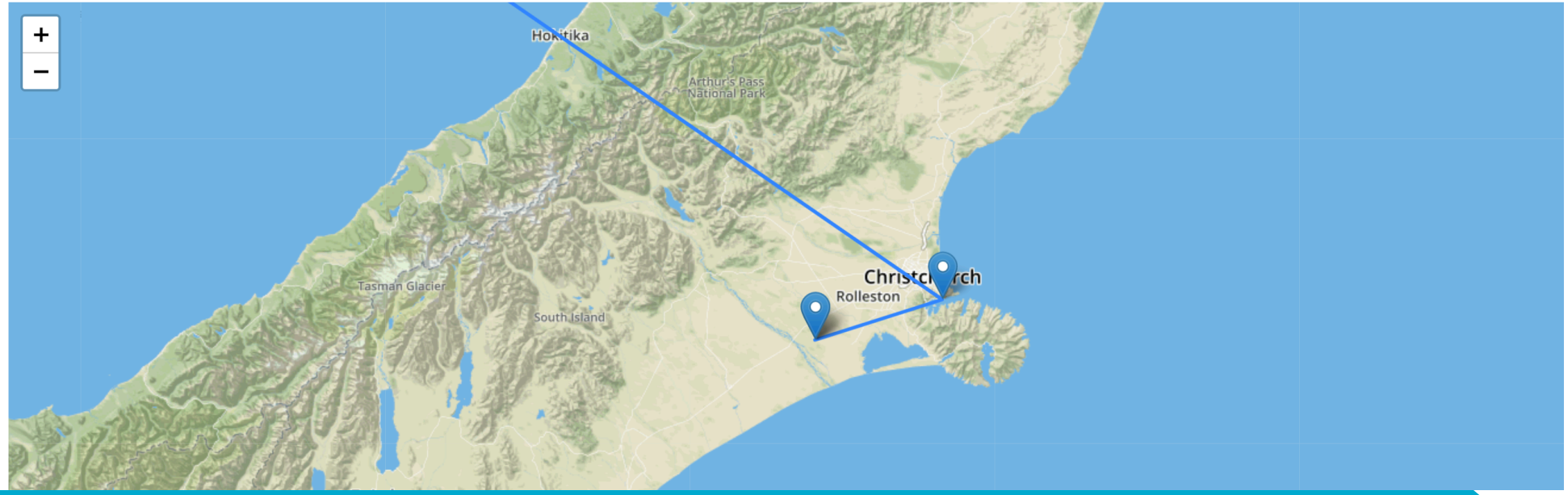
```
OK
command read("demo/deer/data/event-09.xml")
OK
command read("demo/deer/data/event-10.xml")
```

```
command track("urn:epc:id:sgtin:94130000.01420.2")

query currentModel filter { isAbout(_, "Carton-2") }

command toDotFile(currentModel, "demo/deer/out/client-tracking1.dot", display = true)

query toDot(currentModel)
```

Send Query

0 1 2

Json | Json Diff | Graph | **Map**



Conclusions and Future Work

- Developed Fusemate situational awareness system
- Fusemate = Logic Programming + Belief Revision + Scala programming language
- Experimented with Deer supply chain case study
- Future work
  - User interface
  - More case studies
  - Integration with video tracking
  - Probabilities
  - Temporal logic $\Box t \;.\; \text{shipped}(B) \rightarrow \Diamond s \;.\; s \leq t + 5 \wedge \text{received}(B)$
  - Ontologies